Querview

- Equation in'vy
- Ophimizaltor

$$
\begin{aligned}
& f(x)=y \quad g(x)=0 \\
& g(x)=f(x)-y
\end{aligned}
$$

Applications:

$$
\begin{aligned}
\rightarrow \sqrt{y} & <x \Leftrightarrow \quad y=x^{2} \\
\cdot \frac{1}{b} & =x \quad \text { Nowt on's ind hod } \\
& \Leftrightarrow 5 x-1=0
\end{aligned}
$$



$$
f\left(\begin{array}{c}
1 \downarrow \\
\rho \\
v
\end{array}, \theta\right)=\left(\begin{array}{c}
\operatorname{dis}, \\
\vdots \\
\vdots \\
d_{i} l_{n}
\end{array}\right)
$$

Grash

$$
\mathcal{F}\binom{\text { joint anglel }}{\text { joint anglet }}=\left(\begin{array}{l}
x \\
y \\
z
\end{array}\right)
$$

Solving Nonlinear Equations
What is the goal here?


$$
e_{c}^{e_{k+1}=C \cdot e_{k} \mid e_{k}=b_{k}^{\prime} a_{k}}
$$

## Bisection Method

Assume continuos function $f$ has a zero on the interval $[a, b]$ and

$$
\operatorname{sign}(f(a))=-\operatorname{sign}(f(b))
$$

Perform binary search: check sign of $f((a+b) / 2)$ and define new search interval so that ends have opposite sign.
Demo: Bisection Method
What's the rate of convergence? What's the constant?

Newton's Method

$$
\begin{aligned}
& f(x)=0 \\
& \tilde{f}\left(x_{k}+h\right)=f\left(x_{k}\right)+h \cdot f^{\prime}\left(x_{k}\right) \\
& h \cdot f^{\prime}\left(x_{k}\right)=\text { Derive Newton's method. } \\
& h=-\frac{f\left(x_{k}\right)}{f\left(x_{k}\right)} \\
& f\left(x_{k}\right)
\end{aligned}
$$

$$
\begin{aligned}
& x_{k+1}=x_{k}+h=x_{k}-\frac{f\left(x_{k}\right)}{f^{1}\left(x_{k}\right)} \\
& e_{k y 1} \leq c \cdot e_{k}^{2}
\end{aligned}
$$

Demo: Newton's method
Demo: Convergence of Newton's Method

What are some drawbacks of Newton?

## Secant Method

What would Newton without the use of the derivative look like?

## Demo: Secant Method

In-class activity: Nonlinear equations in 1D

## Outline

Python, Numpy, and Matplotlib Making Models with Polynomials Making Models with Monte Carlo
Error, Accuracy and Convergence Floating Point
Modeling the World with Arrays
The World in a Vector
What can Matrices Do?
Graphs
Sparsity
Norms and Errors
The 'Undo' Button for Linear
Operations: LU
Repeating Linear Operations: Eigenvalues and Steady States
Eigenvalues: Applications

Approximate Undo: SVD and Least Squares
SVD: Applications
Solving Funny-Shaped Linear
Systems
Data Fitting
Norms and Condition
Numbers
Low-Rank Approximation
Interpolation
Iteration and Convergence
Solving One Equation

## Solving Many Equations

Finding the Best: Optimization
in 1D
Optimization in $n$ Dimensions

