

Unit Roundoff

Unit roundoff or machine precision or machine epsilon or $\varepsilon_{\rm mach}$ is the smallest number such that

$$\mathsf{float}(1+\varepsilon) > 1.$$

▶ Technically that makes $\varepsilon_{\mathsf{mach}}$ depend on the rounding rule.

Assuming round-towards-instity, in the above system, $\varepsilon_{\rm mach} = (0.00001)_2. \label{eq:emach}$

- ▶ Note the extra zero.
- ▶ Another, related, quantity is *ULP*, or *unit in the last place*.

$$(\varepsilon_{\rm mach}=0.5\,{\rm ULP})$$

FP: Relative Rounding Error

What does this say about the relative error incurred in floating point calculations?

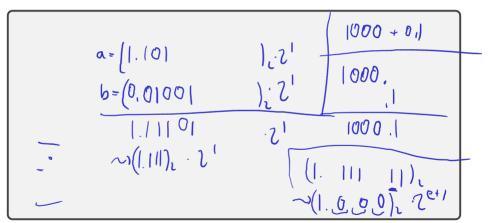
FP: Machine Epsilon

What's that same number for double-precision floating point? (52 stored bits in the significand, 53 total)

Demo: Floating Point and the Harmonic Series [cleared]

Implementing Arithmetic

How is floating point addition implemented? Consider adding $a=(1.101)_2\cdot 2^1$ and $b=(1.001)_2\cdot 2^{-1}$ in a system with three stored bits (four total) in the significand.



Problems with FP Addition

What happens if you subtract two numbers of very similar magnitude? As an example, consider $a = (1.1011)_2 \cdot 2^0$ and $b = (1.1010)_2 \cdot 2^0$.

$$a = (1, 1011)_{2}$$

$$b = (1.1010)_{2}$$

$$a \cdot b = (0.0001)_{2}$$

$$1. (77.7.7.4)$$

Demo: Catastrophic Cancellation [cleared]

Supplementary Material

- ▶ Josh Haberman, Floating Point Demystified, Part 1
- ▶ David Goldberg, What every computer programmer should know about floating point
- ► Evan Wallace, Float Toy

Outline

Introduction to Scientific Computing

Systems of Linear Equations Theory: Conditioning Methods to Solve Systems LU: Application and Implementation

Linear Least Squares

Eigenvalue Problems

Nonlinear Equations

Optimizatio

Interpolation

Numerical Integration and Differentiation

Initial Value Problems for ODE

Boundary Value Problems for ODE

Partial Differential Equations and Sparse Linear Algebra

Fast Fourier Transforn

Additional Topics

Solving a Linear System

Given:

ightharpoonup m imes n matrix A

Az=6 ► *m*-vector **b**

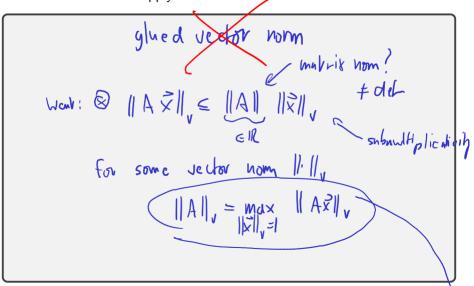
What are we looking for here, and when are we allowed to ask the question?

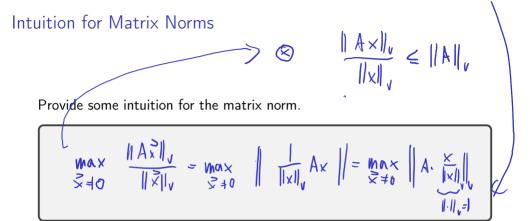
· n-vector & s.t. · restrict to m=n . solutions may notes ist, may not be unique 63! for A non singular.

Next: Want to talk about conditioning of this operation. Need to measure distances of matrices.

Matrix Norms

What norms would we apply to matrices?





Identifying Matrix Norms

What is $||A||_1$? $||A||_{\infty}$?

How do matrix and vector norms relate for $n \times 1$ matrices?

Demo: Matrix norms [cleared]

Properties of Matrix Norms

Matrix norms inherit the vector norm properties:

- $||A|| > 0 \Leftrightarrow A \neq 0.$
- $| \gamma A | = | \gamma | | A |$ for all scalars γ .
- ▶ Obeys triangle inequality $||A + B|| \le ||A|| + ||B||$

But also some more properties that stem from our definition: