#### Recap: Norms

What's a norm?

Define norm.

- positive dofiniteness - semilinenily - triungle inequality

#### Norms: Examples

$$\left\|\left(\frac{1}{||x||}\right)\right\| = \frac{1}{||x||} + ||x|| = 1$$

Examples of norms?



x m

18

 $\leq \|\mathbf{x}\| + \|\mathbf{y}\| = 2$ 

# Norms: Which one?

Does the choice of norm really matter much?



 $\times \epsilon \mathbb{N}^{2}$ 

## Norms and Errors

If we're computing a vector result, the error is a vector. That's not a very useful answer to 'how big is the error'. What can we do?



 $d(\bar{x},\bar{y}) = || x - y||$ 

### Forward/Backward Error

Suppose *want* to compute y = f(x), but *approximate*  $\hat{y} = \hat{f}(x)$ . What are the forward error and the backward error?



# Forward/Backward Error: Example

Suppose you wanted  $y = \sqrt{2}$  and got  $\hat{y} = 1.4$ . What's the (magnitude of) the forward error?



0,000 5 46

0.000 547

## Forward/Backward Error: Example

Suppose you wanted  $y = \sqrt{2}$  and got  $\hat{y} = 1.4$ . What's the (magnitude of) the backward error?

$$x = 1.96$$
Backward error:  
Relative backward error  

$$\frac{|3x| \approx |1.96 \cdot 2| = 0.04}{|x| \approx 0.02}$$

J(x)=5x

## Forward/Backward Error: Observations

What do you observe about the relative manitude of the relative errors?

#### Sensitivity and Conditioning

What can we say about amplification of error?

abs 
$$\neg |y - y| \leq K_{abs} |x - x|$$
  
is in the second of th

 $\frac{|y-\hat{y}|}{|y|} \leq |k_{vel}| \cdot \frac{|x-\hat{x}|}{|x|}$ 

# Example: Condition Number of Evaluating a Function

y = f(x). Assume f differentiable.



Demo: Conditioning of Evaluating tan [cleared]

$$\int (x + \Delta x) \approx \int (x) + \Delta x \cdot f(x) \approx \int (x) + \Delta x \cdot f(x)$$

## Stability and Accuracy

Previously: Considered problems or questions.

Next: Considered *methods*, i.e. computational approaches to find solutions. When is a method *accurate*?

When is a method *stable*?