

September 17, 2024

## Announcements

- HW 1 graded
- Exam 1 live

---

## Goals

- residual  $\rightarrow$  est. error
- $\frac{\| \Delta A \|}{\| A \|}$
- orth SVD, matr. norm
- LU

## Review

$$\| AB \| \leq \| A \| \| B \|$$

$$\rightarrow \| Ax \| \leq \| A \| \| x \|$$

submultiplicativity

rel. output error  $\leq \kappa \cdot$  rel. input error

linear solves:

$$Ax = b$$

$\uparrow$   $\uparrow$   
sol, output rhs input

$$\kappa(A) = \| A \| \| A^{-1} \|^1$$

$$\kappa(A) = 0.5$$

$\parallel$

$$\| A \| \| A^{-1} \| \geq \| AA^{-1} \| = \| I \| = 1$$

## Residual Vector

What is the **residual vector** of solving the linear system

$$\mathbf{b} = A\mathbf{x}?$$

$$\vec{r} = \vec{b} - A\vec{x}$$

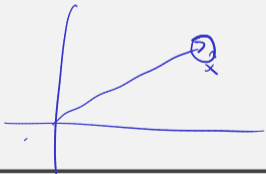
## Residual and Error: Relationship

$$A\vec{x} = \vec{b} \Leftrightarrow \vec{x} = A^{-1}\vec{b}$$

How do the (norms of the) residual vector  $\mathbf{r}$  and the error  $\Delta\mathbf{x} = \mathbf{x} - \hat{\mathbf{x}}$  relate to one another?

$$\|\Delta\vec{x}\| = \|\vec{x} - \hat{\vec{x}}\| = \|A^{-1}(\vec{b} - A\hat{\vec{x}})\| = \|A^{-1}\vec{r}\|$$
$$\frac{\|\Delta\vec{x}\|}{\|\vec{x}\|} \approx \frac{\|A^{-1}\vec{r}\|}{\|\hat{\vec{x}}\|} \leq \frac{\|A^{-1}\| \|\vec{r}\|}{\|\vec{x}\|} = \kappa(A) \frac{\|\vec{r}\|}{\|A\| \|\hat{\vec{x}}\|} \leq \kappa(A) \frac{\|\vec{r}\|}{\|A\hat{\vec{x}}\|}$$

$\uparrow$   
"rel. error"



$\uparrow$   
computable

## Changing the Matrix

So far, only discussed changing the RHS, i.e.  $Ax = b \rightarrow A\hat{x} = \hat{b}$ .  
The matrix consists of FP numbers, too—it, too, is approximate. I.e.

$$Ax = b \rightarrow \hat{A}\hat{x} = b.$$

What can we say about the error due to an approximate matrix?

$$\begin{aligned}\Delta \vec{x} &= \hat{\vec{x}} - \vec{x} = A^{-1}(A\hat{\vec{x}} - b) = A^{-1}(A\hat{\vec{x}} - \hat{A}\hat{\vec{x}}) = A^{-1}(A - \hat{A})\hat{\vec{x}} \\ &= A^{-1} \Delta A \hat{\vec{x}}\end{aligned}$$

$$\|\Delta \vec{x}\| = \|A^{-1} \Delta A \hat{\vec{x}}\| \leq \|A^{-1}\| \|\Delta A\| \|\hat{\vec{x}}\|$$

$$\Leftrightarrow \frac{\|\Delta \vec{x}\|}{\|\hat{\vec{x}}\|} \leq \|A^{-1}\| \|A\| \cdot \frac{\|\Delta A\|}{\|A\|} = \kappa(A) \cdot \frac{\|\Delta A\|}{\|A\|}$$

"rel. error" ↗

## Changing Condition Numbers

$$\text{cond}(AB) \leq \text{cond}(A)\text{cond}(B)$$

Once we have a matrix  $A$  in a linear system  $Ax = b$ , are we stuck with its condition number? Or could we improve it?

Left/Right  
Preconditioner<sup>n</sup>

$$Ax = b$$

assume  $\exists M$  so that

$$(MA) \text{ is well-cond.} \Leftrightarrow MAx = Mb$$

$$(AM)$$

$$\Leftrightarrow AMy = b$$

A typical case: use diagonal matrix as the preconditioner. What is the effect in each case?

(demo)

## Recap: Orthogonal Matrices

What's an *orthogonal* (=orthonormal) matrix?

One that satisfies  $Q^T Q = I$  and  $Q Q^T = I$ .

How do orthogonal matrices interact with the 2-norm?

$$\|Q\mathbf{v}\|_2^2 = (Q\mathbf{v})^T(Q\mathbf{v}) = \mathbf{v}^T Q^T Q \mathbf{v} = \mathbf{v}^T \mathbf{v} = \|\mathbf{v}\|_2^2.$$

## Singular Value Decomposition (SVD)

What is the *Singular Value Decomposition* of an  $m \times n$  matrix?



## Computing the 2-Norm

Using the SVD of  $A$ , identify the 2-norm.

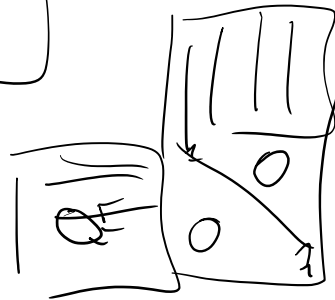
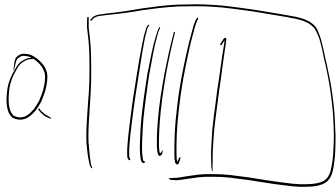
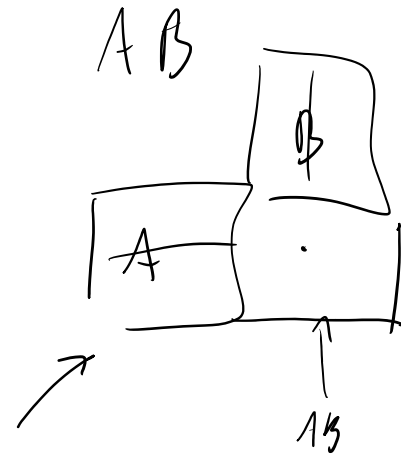
Express the matrix condition number  $\text{cond}_2(A)$  in terms of the SVD:

.



$A M$   $\uparrow$  diag

$M A$   $\uparrow$  diag



$$(\vec{a}, \vec{b}) = \vec{a}^T \vec{b}$$

$v \in \mathbb{R}^n$

$$\|Q \vec{v}\|_2^2 = \begin{pmatrix} Qv & Qv \\ | & \end{pmatrix} = (Qv)^T (Qv)$$

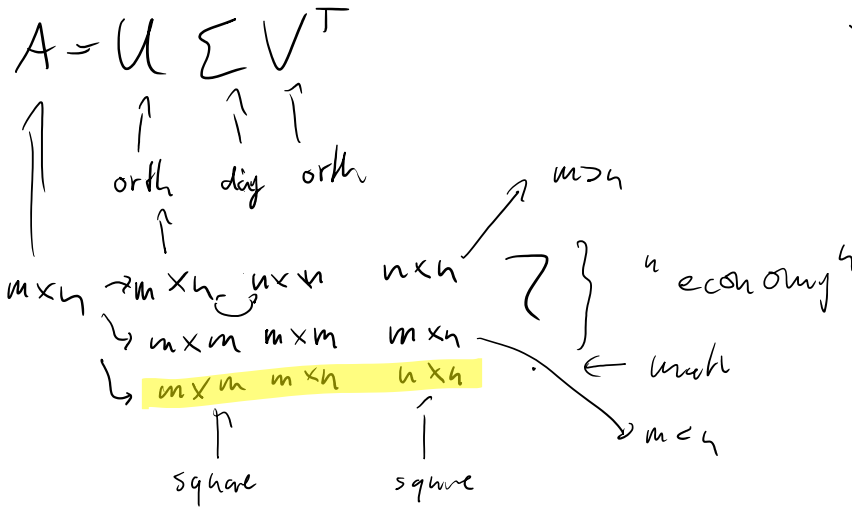
$$\Rightarrow v^T Q^T Q v = v^T v = \|v\|_2^2$$

$$\|Q \vec{v}\|_2 = \|v\|_2$$

$$\|Q A\|_2 = \|A\|_2$$

$$\|A Q\|_2 = \|A\|_2$$

# SVD



$$\|A\|_2 = \|U \Sigma V^T\|_2 = \|\Sigma V^T\|_2 = \|\Sigma\|_2 = \sigma_1$$

$$= \max_i \sigma_i$$

$\kappa(A)$ ?