

October 1, 2024

## Announcements

- Exam 1 grades
- Exam 2
  - HW4 due this week
  - EC for typed HW
  - numericals debug

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## Goals

LSQ sensitivity

QR  $\rightarrow$  LSQ

Computing QR

- Gram-Schmidt

## Review

$$A^T A \vec{x} = A^T \vec{b} \quad \text{⊗}$$

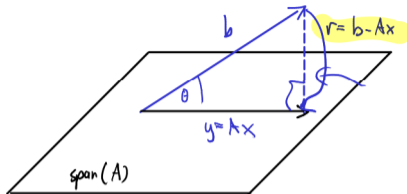
$\rightarrow$  hypothesis generation:

assert ( . . . )  
bool

## Least Squares, Viewed Geometrically (II)

$$Ax \approx b$$

$$\min \|Ax - b\|_2$$



$$A^T A \hat{x} = A^T b$$

$$\hat{x} = (A^T A)^{-1} A^T b$$

Phrase the Pythagoras observation as an equation.

$$\begin{aligned} \perp \text{span}(A) \cdot (b - Ax) &= 0 \\ A^T (b - Ax) &= 0 \quad (\Leftrightarrow) \quad \text{normal equations} \end{aligned}$$

Write that with an orthogonal projection matrix  $P$ .

$$Pb = Ax = A(A^T A)^{-1} A^T b$$

## About Orthogonal Projectors

What is a *projector*?

$$P^2 = P$$

What is an *orthogonal projector*?

$$P \text{ symm. (to show!)}$$

How do I make one projecting onto  $\text{span}\{\mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_l\}$  for orthonormal  $\mathbf{q}_i$ ?

$$Q = \begin{bmatrix} \mathbf{q}_1 & \dots & \mathbf{q}_l \end{bmatrix}$$
$$P = Q Q^T$$

## Least Squares and Orthogonal Projection

Check that  $P = A(A^T A)^{-1}A^T$  is an orthogonal projector onto  $\text{colspan}(A)$ .

$$P^2 = A(A^T A)^{-1}A^T A(A^T A)^{-1}A^T = P$$

$$\cancel{(A^T A)^{-1}A^T}$$

$$\begin{aligned} P^T &= (A(A^T A)^{-1}A^T)^T \\ &= (A^T A)^{-T} A^T = P. \end{aligned}$$

What assumptions do we need to define the  $P$  from the last question?

$A$  full rank.

## Pseudoinverse

$$\vec{x} = A^+ \vec{b} \quad \text{5} \quad \begin{array}{|c|} \hline 3000 \\ \hline \end{array}$$

What is the **pseudoinverse** of  $A$ ?

$$A^+ = (A^T A)^{-1} A^T$$

What can we say about the condition number in the case of a tall-and-skinny, full-rank matrix?

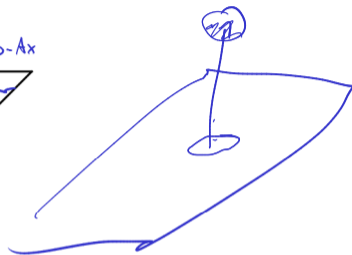
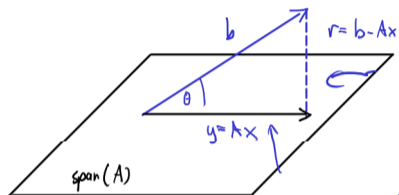
$$\|A\| \|A^{-1}\|$$

$$\begin{aligned} \text{cond}_2(A) &= \|A\|_2 \|A^+\|_2 \\ \rightarrow \text{cond}_2(A) &= \infty \quad \text{if not full rank.} \end{aligned} \quad \text{cond}_2(A^+) = \infty$$

What does all this have to do with solving least squares problems?

$$\vec{x} = A^+ \vec{b}$$

# Sensitivity and Conditioning of Least Squares



Relate  $\|Ax\|$  and  $\|b\|$  with  $\theta$  via trig functions.

$$\cos(\theta) = \frac{\|Ax\|_2}{\|b\|_2}$$

## Sensitivity and Conditioning of Least Squares (II)

Derive a conditioning bound for the least squares problem.

$$\hat{x} = A^+ b$$

$$\Delta \hat{x} = A^+ \Delta b$$

$$\frac{\|\Delta \hat{x}\|}{\|\hat{x}\|} \leq \|A^+\| \cdot \frac{\|\Delta b\|}{\|b\|}$$

$$= \frac{\kappa(A)}{\|A\| \|A^+\|} \cdot \frac{\|b\|}{\|b\|} \cdot \frac{\|\Delta b\|}{\|b\|}$$

$$= \kappa(A) \cdot \frac{\|b\|}{\|A\| \|x\|} \cdot \frac{\|\Delta b\|}{\|b\|}$$

$$\leq \kappa(A) \frac{\|b\|}{\|A\| \|x\|} \frac{\|\Delta b\|}{\|b\|} = \kappa(A) \cdot \frac{1}{\cos(\theta)} \frac{\|\Delta b\|}{\|b\|}$$

What values of  $\theta$  are bad?

$$\theta_j \approx \frac{\pi}{2} \quad / \quad \mathcal{B} \perp \text{spm}(A)$$

## Sensitivity and Conditioning of Least Squares (III)

Any comments regarding dependencies?

sens. of  $Ax \approx b$  depends on  $A$  and  $b$

What about changes in the matrix?

$$\frac{\| \Delta \vec{x} \|_2}{\| \vec{x} \|_2} \leq \left( \kappa(A)^2 + m(0) + \kappa(M) \right) \cdot \frac{\| \Delta A \|}{\| A \|}$$



# Transforming Least Squares to Upper Triangular

$$\|v\|_2 = \|(Q^T b)_{\text{bottom}}\|_2$$

Suppose we have  $A = QR$ , with  $Q$  square and orthogonal, and  $R$  upper triangular. This is called a **QR factorization**.

How do we transform the least squares problem  $Ax \cong b$  to one with an upper triangular matrix?

$$\|Qz\|_2 = \|z\|_2$$

$$\begin{aligned} \|r\|_2 &= \|b - Ax\|_2 \\ &= \|Q^T(b - Ax)\|_2 \\ &= \|Q^T(b - QRx)\|_2 = \|Q^T b - Rx\|_2 \end{aligned}$$

$A \in \mathbb{R}^{m \times n}$   $\rightarrow$  does not affect bottom of  $R$

$\|Q^T b\|_2$   $(R_x)_{\text{top}} = (Q^T b)_{\text{top}}$

## Simpler Problems: Triangular

What do we win from transforming a least-squares system to upper triangular form?

bw subst. on  $(R_x)_{top} = (Q^T y)_{top}$

How would we minimize the residual norm?



## Computing QR

- ▶ Gram-Schmidt
- ▶ Householder Reflectors  $\leftarrow$
- ▶ Givens Rotations

$$\epsilon < \sqrt{\epsilon_{\text{mach}}}$$

$$\left\| \begin{pmatrix} 1 \\ \epsilon \end{pmatrix} \right\|_2 = \sqrt{1^2 + \sqrt{\epsilon_{\text{mach}}^2}}$$

Demo: Gram-Schmidt–The Movie [cleared] (shows *modified* G-S)

Demo: Gram-Schmidt and Modified Gram-Schmidt [cleared]

Demo: Keeping track of coefficients in Gram-Schmidt [cleared]

Seen: Even modified Gram-Schmidt still unsatisfactory in finite precision arithmetic because of roundoff.

**NOTE:** Textbook makes further modification to ‘modified’ Gram-Schmidt:

- ▶ Orthogonalize *subsequent* rather than *preceding* vectors.
- ▶ Numerically: no difference, but sometimes algorithmically helpful.

## Economical/Reduced QR

Is QR with square  $Q$  for  $A \in \mathbb{R}^{m \times n}$  with  $m > n$  efficient?

