

October 22, 2024

## Announcements

- Exam 3
  - collab cheat sheet.
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## Goals

QR

- Equivalence to orth. it.
- Cost

Krylov space methods

## Review

- Schur form

$$A = Q U Q^T$$

- QR iteration

# QR Iteration/QR Algorithm

*orth, it*  
 $X_0 = \text{init guess } A$

$$Q_k R_k = X_k \leftarrow$$

$$X_{k+1} = A Q_k \leftarrow$$

*QR it*

$$\bar{X}_0 = A$$

$$\bar{Q}_k \bar{R}_k = \bar{X}_k \Leftrightarrow \bar{R}_k = \bar{Q}_k^H \bar{X}_k$$

$$\bar{X}_{k+1} = \bar{R}_k \bar{Q}_k$$

$$\bar{X}_{k+1} = \bar{R}_k Q_k = \bar{Q}_k^H X_k \bar{Q}_k = \bar{Q}_k^H \dots \bar{Q}_0^H A Q_0 \dots Q_k \quad (\otimes)$$

$$A^2 = \bar{Q}_0 (\bar{R}_0 \bar{Q}_0) \bar{R}_0 = \bar{Q}_0 \bar{Q}_1 \bar{R}_1 \bar{R}_0$$

*Claim:*

$$Q_k = \bar{Q}_0 \dots \bar{Q}_k$$

$$Q_k^H A Q_k = \bar{X}_k = X_{k+1} \rightsquigarrow \text{forward} \quad \nabla$$

# Proof sketch: Equivalence of QR iteration/Orth. iteration

## Orthogonal Iteration (no bars)

- ▶  $X_0 := A$ 
  - ▶  $Q_0 R_0 := X_0$ ,
  - ▶ where we may choose  $Q_0 = \bar{Q}_0$
  - ▶  $\hat{X}_0 = Q_0^H A Q_0 = Q_0^H Q_0 R_0 Q_0 = R_0 Q_0$
- ▶  $X_1 := A Q_0$ 
  - ▶  $Q_1 R_1 := X_1$ ,  
and because of  $X_1 = Q_0 Q_0^H A Q_0 = Q_0 \hat{X}_0$   
 $Q_0 \bar{Q}_1 \bar{R}_1 \stackrel{Id}{=} Q_0 \hat{X}_0$   
we may choose  $Q_1 = Q_0 \bar{Q}_1 = \bar{Q}_0 \bar{Q}_1$ .
- ▶  $\vdots$

## QR Iteration (with bars)

- ▶  $\bar{X}_0 := A$ 
  - ▶  $\bar{Q}_0 \bar{R}_0 := A$  ✓
- ▶  $\bar{X}_1 := \bar{R}_0 \bar{Q}_0 = \hat{X}_0$ 
  - ▶  $\bar{Q}_1 \bar{R}_1 := \bar{X}_1$
- ▶  $\bar{X}_2 := \bar{R}_1 \bar{Q}_1$ 
  - ▶  $\bar{X}_2 = Q_1^H A Q_1 = \hat{X}_1$
- ▶  $\vdots$

Demo: QR Iteration [cleared]

# QR Iteration: Forward and Inverse

$$(A^{-1})^H = A^{-H} = (A^H)^{-1}$$

QR iteration may be viewed as performing **inverse iteration**. How?

$$\tilde{X}_0 = A$$

$$\bar{Q}_k \bar{R}_k = \tilde{X}_k$$

$$\tilde{X}_{k+1} = \bar{R}_k \bar{Q}_k$$

$(\cdot)^H$

$$\Rightarrow \tilde{X}_0^{-H} = A^{-H}$$

$$(\bar{Q}_k \bar{R}_k)^{-H} = \tilde{X}_k^{-H}$$

$$\bar{Q}_k^{-H} \bar{R}_k^{-H} = (\bar{R}_k^{-1} \bar{Q}_k^H)^{-H}$$

QL factor

$$\tilde{X}_{k+1}^{-H} = \bar{R}_k^{-H} \bar{Q}_k^{-H}$$

$\dots$   
 $\downarrow$

$$X_{k+1} \approx A \delta_k$$

$$X_{k+1} = (A - \sigma I)^{-1} x_k$$

## QR Iteration: Incorporating a Shift

How can we accelerate convergence of QR iteration using shifts?

$$\begin{aligned}\bar{Q}_k \bar{R}_k &= \bar{X}_k - \sigma_k I \Leftrightarrow \bar{R}_k = \bar{Q}_k^H \bar{X}_k - \sigma_k \bar{Q}_k^H \\ \bar{X}_{k+1} &= \bar{R}_k \bar{Q}_k + \sigma_k I \\ \bar{X}_{k+1} &= \bar{R}_k \bar{Q}_k + \sigma_k I = \bar{Q}_k^H \bar{X}_k \bar{Q}_k - \cancel{\sigma_k \bar{Q}_k^H \bar{Q}_k} + \cancel{\sigma_k I}\end{aligned}$$

Demo: QR Iteration [cleared] (Shifted)

## QR Iteration: Computational Expense

A full QR factorization at each iteration costs  $O(n^3)$ —can we make that cheaper?

$$Q, R = \text{la.qr}(X)$$

$$X = R @ Q$$

$$Q_{\text{all}} = Q_{\text{all}} @ Q$$

X

$$H_2 H_1 A H_1^T H_2^T =$$



upper Hessenberg

$O(n^3)$

$H A H^T \rightarrow \text{more zeros!}$

Demo: Householder Similarity Transforms [cleared]

## QR/Hessenberg: Overall procedure

Overall procedure:

1. Reduce matrix to Hessenberg form
2. Apply QR iteration using Givens QR to obtain Schur form

$$\bar{X}_0 = H A H^T$$
$$\tilde{Q}_k \tilde{R}_k = A_k$$

Givens QR  $O(k^2)$

$$\bar{X}_{k+1} = \tilde{R}_k \tilde{Q}_k$$

$O(k^2)$

Why does QR iteration *stay* in Hessenberg form?

$$\nabla \cdot \mathcal{H} = \mathcal{H} \nabla$$

What does this process look like for symmetric matrices?

## Krylov space methods: Intro

What subspaces can we use to look for eigenvectors?

