CS 450: Numerical Anlaysis

Lecture 21

Chapter 7 Numerical Integration and Differentiation
Basic Numerical Quadrature Methods

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April 6, 2018

Integrability and Sensitivity

► Function *f* is integrable if continuous and bounded, in practice a finite number of discontinuities is also ok:

Seek to compute
$$I(f) = \int_a^b f(x) dx$$
, define $||f||_{\infty} = \max_{x \in [a,b]} |f(x)|$

► The condition number of integration is bounded by the distance b-a: Suppose the input function is perturbed $\hat{f}=f+\delta f$, then

$$\begin{split} \delta I &= |I(\hat{f}) - I(f)| \\ &\leq |I(\delta f)| \\ &\leq (b-a)||\delta f||_{\infty} \end{split}$$

Note that this result does not depend on the magnitude of f or its derivatives, which means integration is generally very well-conditioned, which makes sense since integration corresponds to averaging.

Quadrature Rules

ightharpoonup To approximate the integral I(f), compute a weighted sum of points:

$$Q_n(f) = \sum_{i=1}^n w_i f(x_i)$$

- $\{x_i\}_{i=1}^n$ are quadrature nodes or abscissas, $\{w_i\}_{i=1}^n$ are quadrature weights.
- Quadrature rule is closed if $x_1 = a, x_n = b$ and open otherwise.
- ▶ Rule is progressive if nodes of Q_n are a subset of those of Q_{n+1} .
- For a fixed set of n nodes, unique quadrature weights give exact (n-1)-degree quadrature rule:

The rule is exact for all (n-1)-degree polynomials. Express the unique (n-1)-degree polynomial interpolant in the Lagrange basis $p(x) = \sum_{i=1}^n \phi_i(x) f(x_i)$. The quadrature rule is defined by

$$Q_n(f) = I(p(x)) = \sum_{i=1}^n \underbrace{I(\phi_i)}_{w_i} f(x_i).$$

Quadrature Rules and Error

Quadrature weights can be alternatively determined for a rule by solving the moment equations:

$$oldsymbol{V}(oldsymbol{x},\{\phi_i\}_{i=1}^n)oldsymbol{w}=oldsymbol{y}(\{\phi_i\}_{i=1}^n),\quad ext{where}\quad y_i=I(\phi_i)$$

We can approximate the error bound for a polynomial quadrature rule by

$$|I(f) - Q_n(f)| = |I(f - p_{n-1}(x))|$$

$$\leq (b - a)||f - p_{n-1}||_{\infty}$$

$$\leq \frac{b - a}{4n}h^n||f^{(n)}||_{\infty}$$

where $h = \max_{i}(x_{i+1} - x_i)$

Newton-Cotes Quadrature

- Newton-Cotes quadrature rules are defined by equispaced nodes on [a,b]: open: $x_i = a + i(b-a)/(n+1)$, closed: $x_i = a + (i-1)(b-a)/(n-1)$.
- ▶ The *midpoint rule* is the n = 1 open Newton-Cotes rule:

$$M(f) = (b-a)f\left(\frac{a+b}{2}\right)$$

▶ The *trapezoid rule* is the n = 2 closed Newton-Cotes rule:

$$T(f) = \frac{(b-a)}{2}(f(a) + f(b))$$

Simpson's rule is the n=3 closed Newton-Cotes rule:

$$S(f) = \frac{b-a}{6} \left(f(a) + 4f\left(\frac{a+b}{2}\right) + f(b) \right)$$

Error in Newton-Cotes Quadrature

► Consider the Taylor expansion of f about the midpoint of the integration interval m=(a+b)/2:

$$f(x) = f(m) + f'(m)(x - m) + \frac{f''(m)}{2}(x - m)^2 + \dots$$

Integrating the Taylor approximation of f, we note that the odd terms drop,

$$I(f) = \underbrace{f(m)(b-a)}_{M(f)} + \underbrace{\frac{f''(m)}{24}(b-a)^3}_{E(f)} + O((b-a)^5)$$

- ▶ The midpoint rule is third-order accurate (first degree).
- The trapezoid rule is also first degree, despite using higher-degree polynomial interpolant approximation.
- Error can be conveniently approximated by difference of two rules,

$$T(f) - M(f) \approx 3E(f)$$
.

Conditioning of Newton-Cotes Quadrature

▶ We can ascertain stability of quadrature rules, by considering the amplification of a perturbation $\hat{f} = f + \delta f$:

$$|Q_n(\hat{f}) - Q_n(f)| = |Q_n(\delta f)|$$

$$= \sum_{i=1}^n w_i \delta f(x_i)$$

$$\leq ||\boldsymbol{w}||_1 ||\delta f||_{\infty}.$$

Note that we always have $\sum_i w_i = b - a$, since the quadrature rule must be correct for a constant function. So if w is positive $||w||_1 = b - a$, the quadrature rule is stable, i.e. it matches the conditioning of the problem.

▶ Newton-Cotes quadrature rules have at least one negative weight for any $n \ge 11$: More generally, $||\boldsymbol{w}||_1 \to \infty$ as $n \to \infty$ for fixed b-a. This means that the Newton-Cotes rules can be ill-conditioned.

Clenshaw-Curtis Quadrature

▶ To obtain a more stable quadrature rule, we need to ensure the integrated interpolant is well-behaved as *n* increases:

Chebyshev quadrature nodes ensure that interpolant polynomial has bounded coefficients so long as f is bounded, since the Vandermonde system defining its coefficients is well-conditioned. Formally, it can be shown that $w_i > 0$ for Chebyshev-node (Clenshaw-Curtis) quadrature.