

Today

- Interpolation
- Quadrature

Announcements:

- Examlet 4 dates
- Examlet 3 material
- DLMF

Interpolation Error

If f is n times continuously differentiable on a closed interval I and $p_{n-1}(x)$ is a polynomial of degree at most $n-1$ that interpolates f at n distinct points $\{x_i\}$ ($i = 1, \dots, n$) in that interval, then for each x in the interval there exists ξ in that interval such that

$$f(x) - p_{n-1}(x) = \frac{f^{(n)}(\xi)}{n!} (x - x_1)(x - x_2) \cdots (x - x_n).$$

$\leq h^n$
error is 0 at the nodes

$$y(t) = R(t) - \frac{R(x)}{w(x)} w(t)$$

$$R(t) = f(t) - p_{n-1}(t) \leftarrow$$

$$\underline{R^{(n)}(t)} = f^{(n)}(t) - 0$$

$$\begin{aligned} |x - x_2| &\leq h \\ |x - x_1| &\leq h \end{aligned}$$

Interpolation Error: Proof cont'd

$$Y(t) = R(t) - \frac{R(x)}{W(x)} W(t) \quad \text{where} \quad W(t) = \prod_{i=1}^n (t - x_i)$$

$$\underbrace{t=x \rightarrow Y(x)=0}_1$$

$$\underbrace{t=x_i \rightarrow Y(x_i)=0}_n$$

$\rightarrow Y$ has $n+1$ roots

$\rightarrow Y^{(n)}(\xi) = 0$ exists Rolle's theorem

$$Y^{(n)}(t) = \underbrace{f^{(n)}(t)} - \frac{R(x)}{W(x)} n!$$

$$0 = f^{(n)}(\xi) - \frac{R(x)}{W(x)} n!$$

$$R(x) = \frac{f^{(n)}(z)}{n!} W(z)$$

Error Result: Connection to Chebyshev

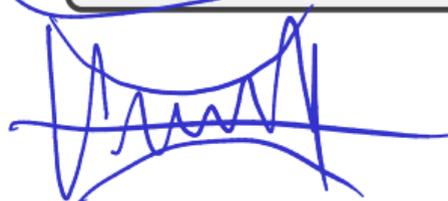
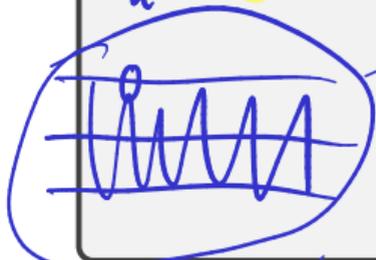
What is the connection between the error result and Chebyshev interpolation?

$$\text{error}(x) \approx W(x) = \prod_{i=1}^n (x - x_i)$$

If $x_i =$ roots of T_n
→ chebyshev polys

controlled by choosing good nodes

$$T_n(x) = \cos(n \cos^{-1}(x))$$



Error Result: Simplified From

Boil the error result down to a simpler form.

$f(x) - p_{n-1}(x) = \frac{f^{(n)}(\xi)}{n!} \omega(x)$

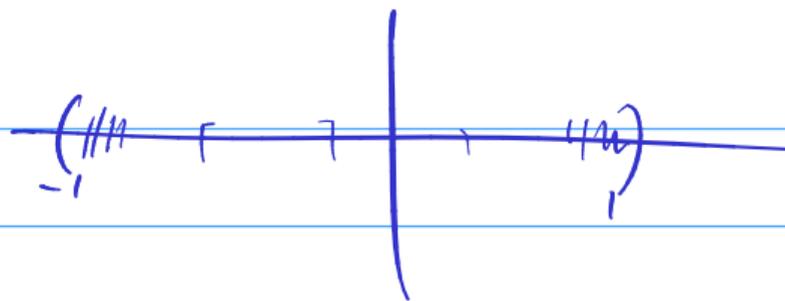
Interpolation error $\leq C(f^{(n)}) h^n$

$h = \text{length of the interval}$

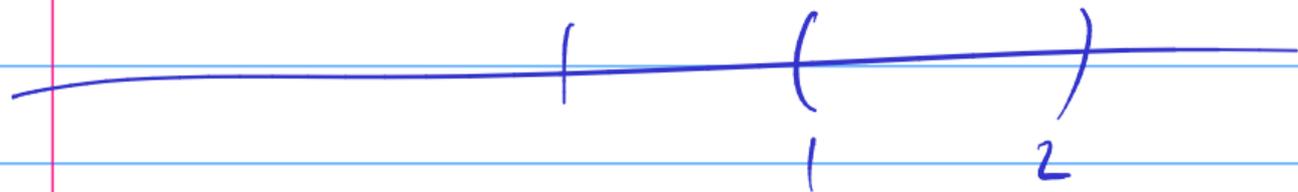
Demo: Interpolation Error

$\in C^1$

$\in C^2$



Cheb nodes



Going piecewise: Simplest Case

repeat

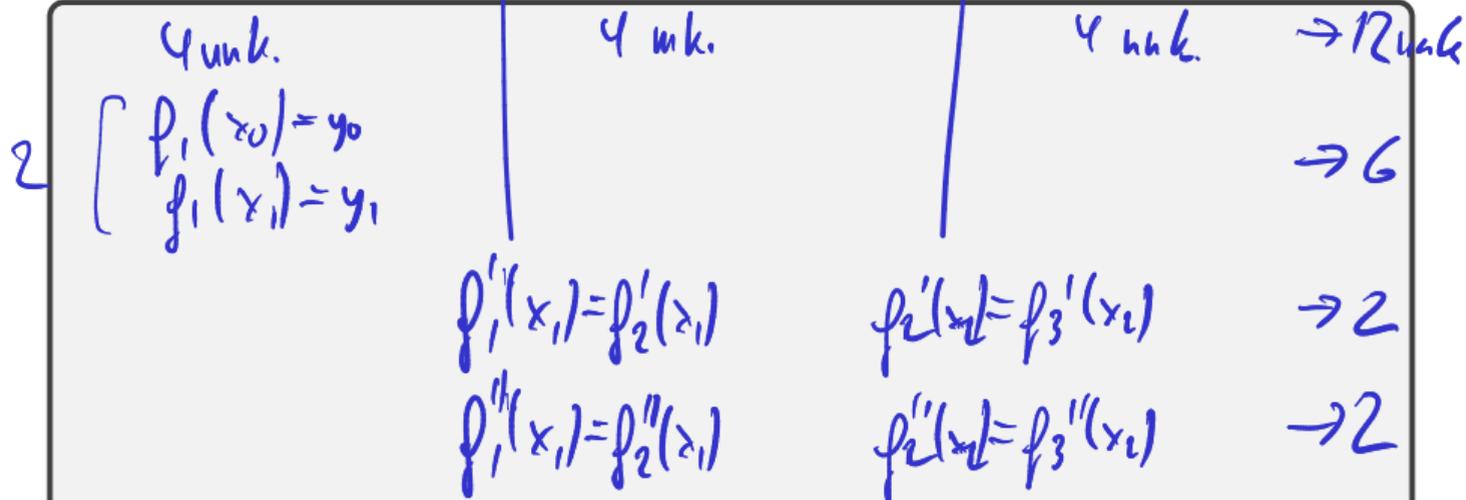
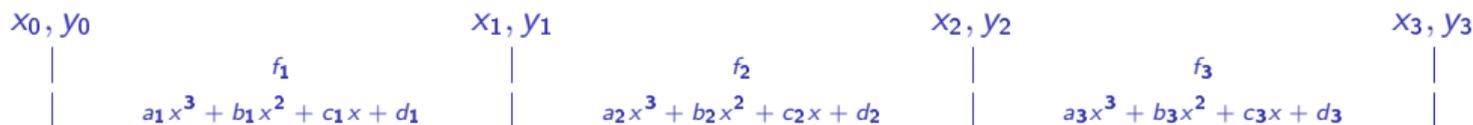
Construct a piecewise linear interpolant at four points.

x_0, y_0		x_1, y_1		x_2, y_2		x_3, y_3
	$f_1 = a_1x + b_1$		$f_2 = a_2x + b_2$		$f_3 = a_3x + b_3$	
	2 unk.		2 unk.		2 unk.	
	$f_1(x_0) = y_0$		$f_2(x_1) = y_1$		$f_3(x_2) = y_2$	
	$f_1(x_1) = y_1$		$f_2(x_2) = y_2$		$f_3(x_3) = y_3$	
	2 eqn.		2 eqn.		2 eqn.	

Why three intervals?

(repeat in middle if you need more)

Piecewise Cubic ('Splines')



Number of cond: $2N_{\text{intervals}} + 2N_{\text{midpts}}$

$$N_{\text{intervals}} - 1 = N_{\text{midpoints}}$$

$$\begin{aligned} \# \text{conds} & \quad 2N_{\text{intervals}} + 2N_{\text{intervals}} - 2 \\ & = 4N_{\text{intervals}} - 2 \end{aligned}$$

$$\# \text{unk: } 4N_{\text{intervals}}$$

→ need 2 extra extra conditions

→ there are two end pts → one for endpoint

"natural" spline → $f''(x_0) = f''(x_n) = 0$

choice $\rightarrow f'(x_0) = f'(x_3)$

and $f''(x_0) = f''(x_2)$

Piecewise Cubic ('Splines'): Accounting

x_0, y_0		x_1, y_1		x_2, y_2		x_3, y_3
	f_1		f_2		f_3	
	$a_1x^3 + b_1x^2 + c_1x + d_1$		$a_2x^3 + b_2x^2 + c_2x + d_2$		$a_3x^3 + b_3x^2 + c_3x + d_3$	



Outline

Introduction to Scientific Computing

Systems of Linear Equations

Linear Least Squares

Eigenvalue Problems

Nonlinear Equations

Optimization

Interpolation

Numerical Integration and Differentiation

Numerical Integration

Quadrature Methods

Accuracy and Stability

Composite Quadrature

Gaussian Quadrature

Numerical Differentiation

Richardson Extrapolation

Initial Value Problems for ODEs

Boundary Value Problems for ODEs

Partial Differential Equations and Sparse Linear Algebra

Fast Fourier Transform

Additional Topics