

## Today

- composite quad
- num. diff.
- Richardson extrapolation
- diff eq.  $\begin{cases} \text{IVP} \\ \text{BVP} \end{cases}$

## Announcements

- Quiz 24 release ✓
- 4CM assignment 2 ✓
- Example 3 debrief ✓
- Example 4 content ✓
- Order of accuracy; Gaussian quadr.

$$\text{Error}(h) = O(h^n)$$



order of accuracy

<sup>n</sup> If a method is exact for polynomials up to degree  $n-1$ , then often the order of accuracy is  $n$

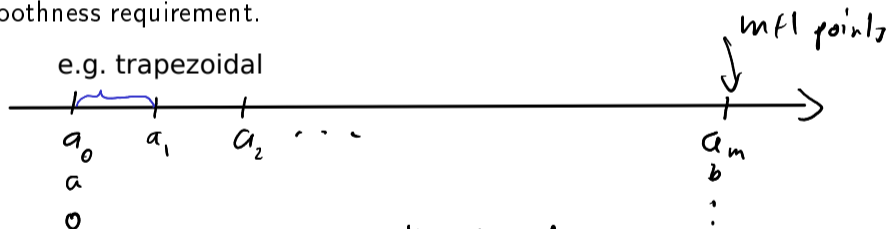
Order of accuracy of Gaussian quad.:  $2n$

# Composite Quadrature



High-order polynomial interpolation requires a high degree of smoothness of the function.

**Idea:** Stitch together multiple lower-order quadrature rules to alleviate smoothness requirement.



Quad w. error  $O(h^q)$

# intervals =  $m$   
length of each interval =  $1/m = h$   
Error for composite:  $\frac{1}{h} O(h^q) = O(h^{q-1})$

↳ composite quad loses an order

## Error in Composite Quadrature

What can we say about the error in the case of composite quadrature?



## Composite Quadrature: Notes

**Observation:** Composite quadrature loses an order compared to non-composite.

**Idea:** If we can estimate errors on each subinterval, we can shrink (e.g. by splitting in half) only those contributing the most to the error.  
(**adaptivity**,  $\rightarrow$  hw)

# Taking Derivatives Numerically

$$\|\vec{v}\|_\infty = \max |v_i|$$

$$\|f\|_\infty = \max_{x \in [a,b]} |f(x)|$$

→ must be ill-

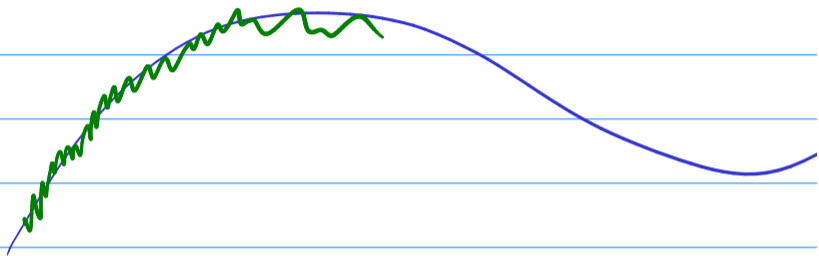
Why shouldn't you take derivatives numerically?

e.g.  $\sin(\alpha x)$

- unbounded:  $\|p\|_\infty \leq \epsilon \rightarrow \|p'\|_\infty$  can still be unbounded
- has a nullspace  $c' = 0$

Demo: Taking Derivatives with Vandermonde Matrices

$$\rightarrow \|A\|, \|A^{-1}\| \rightarrow \infty$$



↳ derivative of noise drowns out the derivative of the signal



$$f'(x) = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}$$

→ cancellation as a numerical method



h

Interpolation:  $O(h^n)$

Quadrature:  $O(h^{n+1})$

Diff.:  $O(h^{n+1})$

## Finite Differences

$$f'(x) \approx \frac{f(x+h) - f(x)}{h}$$

$\uparrow$  "finite difference"

$$f(x+h) = f(x) + f'(x)h + f''(x) \cdot \frac{h^2}{2} + \dots$$

Error:  $f''(x) \frac{h^2}{2} + \text{HOT}$

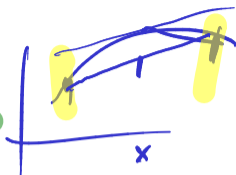
$\hookrightarrow O(h) \rightarrow$  first order accurate

## More Finite Difference Rules

Similarly:

$$f'(x) = \frac{f(x+h) - f(x-h)}{2h} + O(h^2)$$

(Centered differences)



Can also take higher order derivatives:

$$f''(x) = \frac{f(x+h) - 2f(x) + f(x-h)}{h^2} + O(h^2)$$

Can find these by trying to match Taylor terms.

Alternative: Use linear algebra with interpolate-then-differentiate to find FD formulas.

[Demo: Finite Differences vs Noise](#)

[Demo: Floating point vs Finite Differences](#)

$$f(x) \approx \sum_{i=0}^{n-1} \alpha_i \varphi_i(x)$$

$$\vec{\alpha} = V^{-1} f(\vec{x}) \rightarrow f(x) = V \vec{\alpha}$$

$$(V)_{ij} = (\varphi_j(x_i)) \rightarrow f'(x) \approx \sum_{i=0}^{n-1} \alpha_i \varphi_i'(x)$$

$$f'(\vec{x}) = \underbrace{V' V^{-1}}_{\text{differentiation matrix}} f(\vec{x})$$

# Richardson Extrapolation

If we have two estimates of something, can we get a third that's more accurate? Suppose we have an approximation  $F = \tilde{F}(h) + O(h^p)$  and we know  $\tilde{F}(h_1)$  and  $\tilde{F}(h_2)$ .

$$F = \tilde{F}(h) + a h^p + O(h^q) \quad \text{of course } q = p+1$$

$$F = \alpha \tilde{F}(h_1) + \beta \tilde{F}(h_2) + O(h^q)$$

$$\alpha \cdot a \cdot h_1^p + \beta \cdot a \cdot h_2^p = 0 \quad / \quad \alpha + \beta = 1$$

$$\alpha = \frac{-h_2^p}{h_1^p - h_2^p}$$

$$\alpha = \frac{-\frac{1}{2}}{1 - \frac{1}{2}} = -1$$

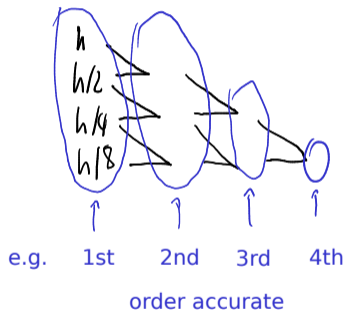
$$\beta = 1 - \alpha$$

$$\frac{1}{2}$$

# Richardson Extrapolation: Observations, Romberg Integration

Important observation: Never needed to know  $a$ .

**Idea:** Can repeat this for even higher accuracy.



Carrying out this process for quadrature is called **Romberg integration**.

**Demo: Richardson with Finite Differences**

## In-Class Activity: Differentiation and Quadrature

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# Outline

Introduction to Scientific Computing

Systems of Linear Equations

Linear Least Squares

Eigenvalue Problems

Nonlinear Equations

Optimization

Interpolation

Numerical Integration and Differentiation

**Initial Value Problems for ODEs**

Existence, Uniqueness, Conditioning

Numerical Methods (I)

Accuracy and Stability

Stiffness

Numerical Methods (II)

Boundary Value Problems for ODEs

Partial Differential Equations and Sparse Linear Algebra

Fast Fourier Transform

Additional Topics