

Parallel Numerical Algorithms

Chapter 7 – Differential Equations

Section 7.3 – Particle Methods

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Outline

- 1 Particle Simulations
 - N-Body Problems
 - Symplectic Integrators
 - Potentials
- 2 All-Pair Interactions
 - Particle Decomposition
 - Force Decomposition
- 3 Distance-Limited Interactions
 - Spatial Decomposition
 - Neutral Territory Methods
 - Smooth Particle Mesh Ewald Method
 - Hierarchical Methods

N-Body Problems

- Many physical systems can be modeled as collection of interacting particles
- “*Particles*” vary from atoms in molecule to planets in solar system or stars in galaxy
- Particles exert mutual *forces* on each other, such as gravitational or electrostatic forces

N-Body Model

- Newton's Second Law

$$F = m a$$

- Force between particles at positions x_i and x_j

$$f(x_i, x_j)$$

- Overall force on i th particle

$$F(x_i) = \sum_{j=1}^n f(x_i, x_j)$$

N-Body Simulation

- System of ODEs

$$F(x_i) = m_i \frac{d^2 x_i}{dt^2}$$

- *Verlet* time-stepping scheme

$$x_i^{k+1} = 2x_i^k - x_i^{k-1} + (\Delta t)^2 F(x_i^k)/m_i$$

- For long time integration, *symplectic* integrators are appropriate (preserve geometric properties, such as orbits)
- Velocity Verlet scheme used in molecular dynamics to preserve energy
- $\mathcal{O}(n^2)$ cost of evaluating force at each time step dominates overall computational cost

Molecular Dynamics

A molecular dynamics simulation performs the following calculations at every *timestep*

- 1 Calculate non-bonded forces F_{ij} for each pair (i, j) of particles (atoms)
- 2 Integrate non-bonded forces $f_i = \sum_j F_{ij}$
- 3 Consider local bonded many-particle interactions and update f_i
- 4 Update acceleration $a_i = f_i/m_i$ and velocity v_i using a_i
- 5 Compute new particle position x_i using v_i and a_i

Van der Waals Forces

Short-range atomic interactions governed by electronic coupling (Pauli exclusion principle)

- Molecular bonds typically treated specially
- Short-range 'non-bonded' forces modelled by *Van der Waals (dipole) potential*
- These are based on approximations to the electronic wavefunction
- A simple formulation is the Lennard-Jones potential

$$F_{\text{LJ}}(x_i, x_j) = \frac{1}{x_i - x_j} \left(\frac{\sigma_{ij}^{(A)}}{|x_i - x_j|^{12}} - \frac{\sigma_{ij}^{(B)}}{|x_i - x_j|^6} \right)$$

where $\sigma_{ij}^{(A)}$ and $\sigma_{ij}^{(B)}$ depend on the types of atoms particles i and j are

Electrostatic Forces

Electrostatic potentials describe Coulomb's law for electric fields due to charge

- They decay slowly relative to Van Der Waals interactions

$$F_{\text{EC}}(x_i, x_j) = (x_i - x_j) \frac{q_i q_j}{|x_i - x_j|^3}$$

where q_i and q_j are the charges of particles at x_i and x_j

- Coulomb potential interactions are well-approximated using fast solvers

Particle Decomposition

The simplest way to parallelize MD is by *particle decomposition*

- Fine-grained tasks are particles, each processor is assigned n/p of them
- Processors exchange particles in a ring, computing forces from received particles to original n/p

- Parallel execution time is

$$T_p(n) = O(p\alpha + n\beta + (n^2/p)\gamma)$$

- Memory footprint is minimal $M_p = \Theta(n)$
- Can reduce latency cost by working with larger subsets of particles

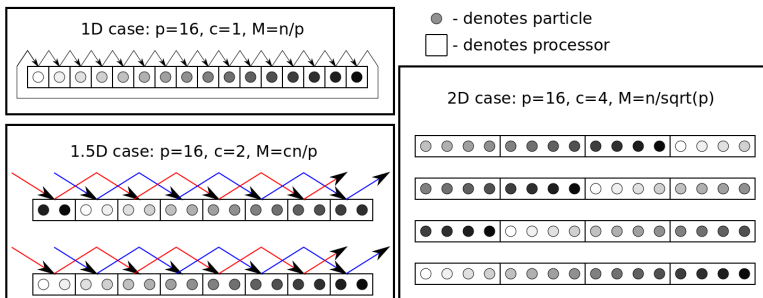
Force Decomposition

Force decomposition achieves lower communication volume

- Fine-grained tasks are forces, coarse-grained (aggregated) tasks are square blocks of forces
- Assignment/scheduling of aggregated tasks on processors must control for memory usage
- Each processor gets $s \times t$ block ($st = n^2/p$, $s \leq t$), accumulates forces for s particles, by streaming in t in t/s steps and reducing at the end
- Memory footprint per processor is $M_p = ps$, time is

$$T_p(s, t) = O\left(\left(\frac{t}{s} + \log p\right)\alpha + t\beta + \frac{n^2}{p}\gamma\right)$$

Algorithms for All-pairs Force Calculation



- 1D – particle decomposition ($c = 1, s = n/p, t = n$)
- 2D – force decomposition ($c = \sqrt{p}, s = n/\sqrt{p}, t = n/\sqrt{p}$)
- 1.5D – memory-constrained force decomposition ($M_p = cn^2, s = cn/p, t = n/c$)

Decay of Forces with Distance

Molecular dynamics is typically done without explicitly computing all particle interactions

- Van der Waals interactions decay very rapidly and can be ignored for far-away particles
- Electrostatic forces can be computed by fast solvers
 - Electrostatic potential obeys the Poisson equation
 - The gravitational potential (used for cosmological simulation) is also Poisson
 - While pairwise interactions decay slowly, the aggregate potential due to long-range forces will be a smooth function

Cutoff Radius

For molecular dynamics, interactions decoupled as follows

- Compute Van der Waals interactions of all particle pairs (i, j) within distance $|x_i - x_j| \leq r_c$
- Fit a 3D charge density grid to the particle charges
- Solve the 3D Poisson equation on the grid via 3D FFT or Multigrid to obtain potential at grid-points
- Extrapolate potential from grid to compute electrostatic forces on particles
 - Force is given by the spatial gradient of potential
 - *B-splines* provide a basis with compact spatial support and easy computation of derivatives

Spatial Decomposition

Domain is $n^{1/3} \times n^{1/3} \times n^{1/3}$ box with uniform density

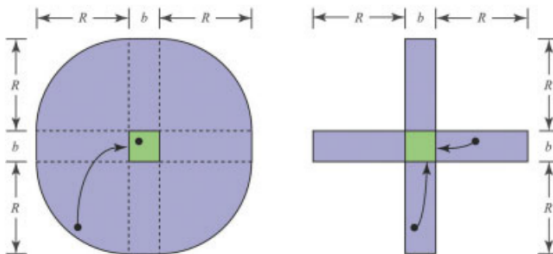
- MD simulations are typically done inside ‘solute’ (water), and have uniform density
- Uniform density does not necessarily hold in other domains, e.g. cosmological simulations
- Fine-grained tasks are unit-volume boxes
- Aggregated-tasks (boxes) are mapped to processors
- Each processor can have subdomain of dimensions $(n/p)^{1/3} \times (n/p)^{1/3} \times (n/p)^{1/3}$
- To compute forces onto all these particles, need all particles within r_c away from subdomain

$$W_p(n, r_c) = O((r_c + (n/p)^{1/3})^3 - n/p) = O(r_c^3 + r_c(n/p)^{2/3})$$

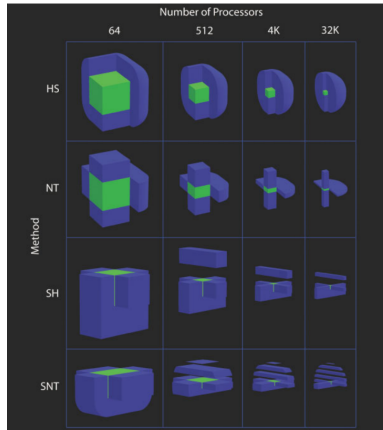
Neutral Territory Methods

Spatial decomposition leverage locality of particles, *neutral territory methods* directly exploit locality of forces

- Allow interactions between particles owned by two different processors to be computed on a third, in *neutral territory*



3D Neutral Territory Methods



Diagrams taken from D. Shaw, “A Fast, Scalable Method for the Parallel Evaluation of Distance-Limited Pairwise Particle Interactions”, 2005

Minimal Import Regions

Assign each processor k is assigned a unique subvolume $X_k \times Y_k \times Z_k$ of dimensions $b_{xy} \times b_{xy} \times b_z$ such that $b_{xy}^2 b_z = n/p$

- Processor k computes interactions of particle pair (i, j) if
 - i and j have a z -coordinate in Z_k and x, y -coordinates within r_c of some element in X_k, Y_k , respectively
 - i and j have x, y -coordinates in X_k, Y_k and a z -coordinate within r_c of some element in Z_k
- The volume of the region (amount of communication) is

$$W_p(n, r_c, b_{xy}, b_z) = O(r_c b_{xy}^2 + r_c b_z b_{xy} + r_c^2 b_z)$$

- Minimizing the import region with respect to b_{xy} and b_z

$$W_p(r_c) = O(r_c (n/p)^{2/3} + \sqrt{r_c^3 n/p})$$

Smooth Particle Mesh Ewald (SPME)

Solve for long range interactions on a $m \times m \times m$ charge grid

- System assumed periodic, which is often valid in MD
- *Ewald summation* is used to split the total potential energy

$$E = \frac{1}{2} \sum_{c \in \mathbb{Z}^3} \sum_{i=1}^n \sum_{j=1}^n \frac{q_i q_j}{|x_i - x_j + cn^{1/3}|} = \frac{1}{2} \sum_{c \in \mathbb{Z}^3} \sum_{i=1}^n \sum_{j=1}^n \frac{q_i q_j}{r_{ij}^{(n)}}$$

into two parts (the form here is slightly simplified)

Ewald Summation

- The first part is a dampened direct summation

$$E_{\text{dir}} = \frac{1}{2} \sum_{c \in \mathbb{Z}^3} \sum_{i=1}^n \sum_{j=1}^n \frac{q_i q_j (1 - \text{erf}(r_{ij}^{(n)} / (\sqrt{2}\sigma)))}{r_{ij}^{(n)}}$$

where $\text{erf}(x) = \frac{2}{\pi} \int_0^x e^{-t^2} dt$ is the Gaussian error function

- The reciprocal term (second part) comes from solving a smooth periodic Poisson equation induced by the Gaussian terms, with exception of the base cell

$$E_{\text{rec}} = \frac{1}{2} \sum_{c \in \mathbb{Z}^3, c \neq (0,0,0)} \sum_{i=1}^n \sum_{j=1}^n \frac{q_i q_j \text{erf}(r_{ij}^{(n)})}{r_{ij}^{(n)}}$$

- A self-term correction is also required to account for the effect of the Gaussian distribution on the base cell

SPME Computational Structure

The forces on particles in SPME are obtained by equations that are derivatives of the energy with respect to position

- SPME with $m \times m \times m$ grid calculates the reciprocal portion as follows
 - B-splines interpolate charge from nearby region of particles

$$T_p(n, m) = O(\alpha + (n/p)^{2/3}\beta + (m^3/p)\gamma)$$

- The grid convolution by 3D FFT for $p \leq m^{5/2}$ takes time

$$T_p(m) = O(\log p\alpha + (m^3/p)\beta + (m^3 \log(m)/p)\gamma)$$

- Extrapolating potential from grid to particles

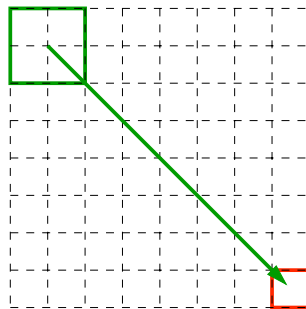
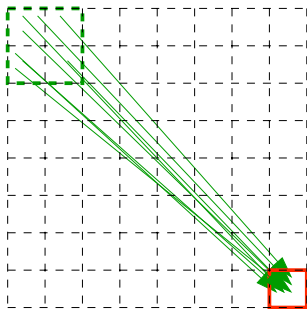
$$T_p(m) = O(\log p\alpha + (m^2/p^{2/3})\beta + (m^3/p)\gamma)$$

Alternative Methods

- Poisson equation on grid can theoretically be solved fastest by multigrid
- SPME can outperform multigrid in practice, achieving high accuracy with a small grid
- Advantage in part due to sensibility of periodicity condition
- Particle simulations with unbalanced particle distributions require different methods
- The *Barnes-Hut* method and the *Fast Multipole Method (FMM)* leverage hierarchical domain partitioning

Tree Partitioning for N-Body Problems

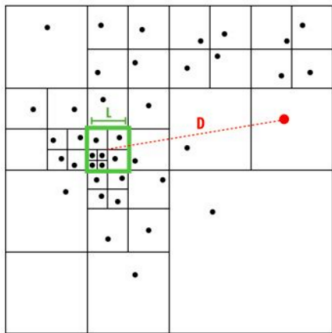
- Tree-based methods such as Barnes-Hut and FMM replace *a set* of forces from far-away particles with *a single* aggregate approximate force



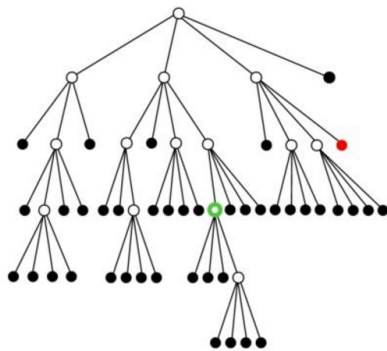
Barnes-Hut

- Barnes-Hut simulations provide a hierarchical spatial decomposition suitable for unbalanced distributions
- Subdivide space recursively until cells contain $O(k)$ particles
 - in 1D, obtain *binary tree*
 - in 2D, obtain *quad tree*
 - in 3D, obtain *oct tree*
- Compute a centered mass/charge for each tree node or r terms of a Taylor series for higher accuracy
- Calculate forces between far-away particles in far-away cells, based on interaction with particle and a mass/charge at a higher-level tree node

Barnes-Hut



Spatial Domain



Quad-Tree Representation

Diagram taken from course webpage of Mowry and Railing (CMU)

Fast Multipole Method (FMM)

FMM obtains linear complexity for integral equations

- Derivations specific to equations, Greengard and Rokhlin originally focused on 2D electrostatics
- In Barnes-Hut leaves interact with tree nodes, in FMM, tree nodes interact with $O(1)$ other tree nodes
- Each node has a *multipole (inner)* and *Taylor (outer)* expansion consisting of $O(\log(1/\epsilon))$ terms for accuracy ϵ
 - Error is controlled by number of terms in expansion
 - A multipole expansion is a special type of Taylor expansion
- *Transformation* operators are defined to 'shift' multipole and Taylor expansions, and to convert between the two

FMM Algorithm

The computation in FMM proceeds as follows

- 1 Perform interactions among particles in neighboring blocks
- 2 Upward pass – generate multipole expansion for every tree node starting from leaves
- 3 Downward pass – generate local expansion for every tree node starting from root

Structure and execution time model is analogous to HSS matrices, but with some differences

- 1 All neighboring cells interact directly
- 2 Amount of work associated with each tree node may vary

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