

Today

- FE Approximation

if $\|u - v_h\| \leq \|u - I_h u\| \stackrel{(\circledast)}{\leq} C h^k \|u\|_{H^k}$
 $v_h \in V_h$

- $\Delta u = f$?

Stokes

- P6

Announcements

- HW5 now due May 6

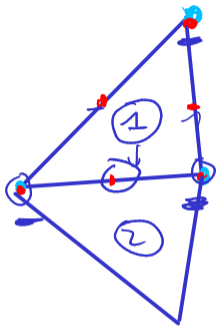
↳ P1, P3 Fixed

- Extra credit?

$$Ax = b$$

$$PAx = Pb$$

$$y = P^T x$$



P^1

P^2

}
r
s
r²
rs
s²



Sobolev Seminorms

$$\rightarrow \|u\|_{k,p} := \sqrt[p]{\sum_{|\alpha| \leq k} \|D_w^\alpha u\|_p^p}$$

$W^{k,p}$

$H^1 = W^{1,2}$

Definition ((k, p)-Sobolev Seminorm)

The Sobolev **seminorm** is given by

$$|u|_{k,p} = \sqrt[p]{\sum_{|\vec{\alpha}|=k} \|D_w^{\vec{\alpha}} u\|_p^p}$$

Conditions on the Mesh

Let Ω be a polygonal domain.



Admissibility (Braess, Def. II.5.1)

A partition (mesh) $\mathcal{T} = \{E_1, \dots, E_M\}$ of Ω into triangular or quadrilateral elements is called **admissible** if

$$\bar{\Omega} = \bigcup_{m=1}^M \bar{E}_m$$



'Nitsche method'

- \times - If $E_i \cap E_j$ is exactly one point, then that point must be a vertex.
- \times - If $E_i \cap E_j$ is more than a point and $i \neq j$, then $E_i \cap E_j$ must be a common edge.

Give an example of a non-admissible partition.

hanging, overlap, curved

Mesh Resolution, Shape Regularity



Definition (Diameter)

$$d(E) = \sup \{ |x-y| : x, y \in E \}$$

Mesh Resolution

When every element has a diameter at most $2h$, then we write \mathcal{T}_h .

Definition (Shape Regularity (Braess, Def. II.5.1))

A family of partitions $\{\mathcal{T}_h\}$ is called **shape regular** if

there exists a number $\kappa > 0$ so that every element $E \in \mathcal{T}_h$ contains a circle of radius $\rho_E \geq h/\kappa$. ^{in-circle crit.}

Cone Conditions



Definition (Lipschitz Domain)

A bounded domain $\Omega \subset \mathbb{R}^n$ is called a **Lipschitz domain** provided that...



for every $x \in \partial\Omega$, there exists a nbh so that $\partial\Omega \cap \text{nbh}$ is the graph of a Lip. function

Lipschitz domains satisfy a **cone condition**:



Theorem (Rellich Selection Theorem (Braess, Thm. II.1.9))

Let $m \geq 0$, let Ω be Lipschitz. Then the imbedding $H^{m+1}(\Omega) \rightarrow H^m(\Omega)$ is **compact**, i.e. any bounded sequence in the range of the imbedding has a convergent subsequence.

The Interpolation Operator

Theorem (Interpolation Operator (Braess, Lemma II.6.2))

Let $\Omega \subset \mathbb{R}^2$ be Lipschitz. Let $t \geq 2$, and z_1, z_2, \dots, z_s are $s := t(t+1)/2$ prescribed points in $\bar{\Omega}$ such that the interpolation operator $I : H^t \rightarrow \mathbb{P}^{t-1}$ is well-defined. Then there exists a constant c so that for $u \in H^t(\Omega)$

$$\|u - Iu\|_{H^t} \leq c |u|_{H^t}$$

Theorem (Approx. for Congruent \triangle (Braess, Remark II.6.5))

Let $E_h := h\hat{E}$, i.e. a scaled version of a reference triangle, with $h \leq 1$. Then, for $0 \leq m \leq t$, there exists a C so that

$$\|u - Iu\|_{H^m(E_h)} \leq C h^{t-m} |u|_{H^t}$$

Approximation for Congruent Triangles: Proof

$$h \leq 1$$

$$E_h = h \hat{E}$$

$$\rightarrow \|u - Iu\|_{H^m(E_h)} \leq Ch^{t-m} |u|_{H^t(E_h)} \quad (0 \leq m \leq t)$$

Let $u \in H^t(E_h)$. Define $v \in H^t(\hat{E})$ by $v(y) = u(hy)$.

$$D_w^\alpha v = h^{|\alpha|} D_v^\alpha u \quad (|\alpha| \leq t)$$

$$\rightarrow |v|_{H^l(\hat{E})}^2 = \sum_{|\alpha|=l} \int_{\hat{E}} (D_w^\alpha v)^2 dx = \sum_{|\alpha|=l} \int_{E_h} (D_w^\alpha u)^2 h^{2l-2} = |u|_{H^l(E_h)}^2 h^{2l-2}$$

$$\|u\|_{H^n}^2 = \sum_{l \leq n} |u|_{H^l}^2 = \sum_{l \leq n} h^{-2l+2} |v|_{H^l}^2 \leq C' h^{-2n+2} \|v\|_{H^n}^2 \quad (h \leq 1)$$

$$\|u - Iu\|_{H^m} \leq C' h^{-m+1} \|v - Iv\|_{H^m} \leq C' h^{-m+1} \|v - Iv\|_{H^t}$$

$$\leq C'' h^{-m+1} |v|_{H^t} \leq C'' h^{t-m} |u|_{H^t}.$$

H^m Polynomial Approximation on Meshes

Definition (Broken Norm)

Given a partition $\mathcal{T}_h = \{E_i\}_{i=1}^M$ and a function u such that $u \in H^m(E_i)$,

$$\|u\|_{H^m, h} := \sqrt{\sum_{m=1}^M \|u\|_{H^m(E_m)}^2}$$

Approximation Theorem (Braess, Theorem II.6.4)

Let $t \geq 2$, suppose \mathcal{T}_h is a shape-regular triangulation of Ω . Then there exists a constant c such that, for $0 \leq m \leq t$ and $u \in H^t(\Omega)$,

$$\|u - I_h u\|_{H^m, h} \leq c h^{t-m} |u|_{H^t}$$

Outline

Introduction

Finite Difference Methods for Time-Dependent Problems

Finite Volume Methods for Hyperbolic Conservation Laws

Finite Element Methods for Elliptic Problems

tl;dr: Functional Analysis

Back to Elliptic PDEs

Galerkin Approximation

Finite Elements: A 1D Cartoon

Finite Elements in 2D

Approximation Theory in Sobolev Spaces

Saddle Point Problems, Stokes, and Mixed FEM

Non-symmetric Bilinear Forms

Discontinuous Galerkin Methods for Hyperbolic Problems

Weak Forms as Minimization Problems

$$a(u, v) = g(v) \quad \forall v \in V$$

Let V be a linear space, and $a : V \times V \rightarrow \mathbb{R}$ a bilinear form, and $g \in V'$.

Theorem (Solutions of Weak Forms are Quadratic Form Minimizers)

If a is SPD, then

$$J(v) = \frac{1}{2} a(v, v) - g(v)$$

attains its minimum over V at u iff $a(u, v) = g(v)$ for all $v \in V$. $A_x < b$

$$u, v \in V \quad t \in \mathbb{R}$$

$$x^T A x$$

$$J(u+tv) = \frac{1}{2} a(u+tv, u+tv) - g(u+tv)$$

$$= J(u) + t [a(u, v) - g(v)] + \frac{t^2}{2} \underline{a(v, v)}$$

If u satisfies $a(u, v) = g(v) \quad \uparrow = 0$ $J(u+tv) > J(u)$.

If J has a min at u , $\forall t \rightarrow J(u+tv)$ has a min at $t=0$, $J'(0) = 0$.

Saddle Point Problems

X, M Hilbert spaces. $a : X \times X \rightarrow \mathbb{R}$ and $b : X \times M \rightarrow \mathbb{R}$ continuous bilinear forms, $f \in X', g \in M'$. Minimize

$$J(u) = \frac{1}{2}a(u, u) - \langle f, u \rangle \quad \text{subject to} \quad b(u, \mu) = \langle g, \mu \rangle \quad (\mu \in M).$$

Apply the method of the Lagrange multipliers.

$$\mathcal{L}(u, \lambda) = \frac{1}{2}a(u, u) - \langle f, u \rangle + \lambda [b(u, \mu) - \langle g, \mu \rangle]$$

Example: Saddle Point Problem in \mathbb{R}^2

$$f(x, y) = x^2 + y^2 \rightarrow \min!$$

$$g(x, y) = x + y = 2$$

$$\nabla \mathcal{L} = 0$$

$$-\nabla f = \lambda \nabla g$$

$$g(x, y) = 0$$

Write down the Lagrangian.

$$\mathcal{L}(x, y, \lambda) = f(x, y) - \lambda g(x, y)$$

Show that $x = y = 1, \lambda = -2$ is a saddle point.