$$u_{tt} = c^2 u_{xx} \qquad ((x,t) \in \mathbb{R} \times [0,T])$$

$$u(x,0) = g(x) \qquad (x \in \mathbb{R})$$

$$\text{with } g(x) = \sin(\pi x).$$

Is this problem well-posed?

No, missing IC was 
$$N_{\ell}(x_{\ell}0)=0$$
 (kell)

Can be rewritten in conservation law form:

$$\Rightarrow \vec{q}_{\ell} + \nabla \cdot \vec{\tau}(q) = s(x_{i}\delta) \qquad q(x_{i}\delta)$$

## Hyperbolic Conservation Laws

ition Laws 
$$\mathbf{q} \in \mathbb{R}^{d}$$

$$\mathbf{x} \in \mathbb{R}^{d}$$

$$\mathbf{q}_{t}(\mathbf{x}, t) + \nabla \cdot \mathbf{F}(\mathbf{q}(\mathbf{x}, t)) = s(x)$$



Why is this called a conservation law?

$$\int_{\mathcal{L}} q_{+} + \nabla \cdot \neq (q) = 0$$

$$\int_{\mathcal{L}} q_{+} + \int_{\mathcal{L}} \nabla \cdot + (q) = 0$$

$$\int_{\mathcal{L}} \int_{\mathcal{L}} q + \int_{\mathcal{L}} \nabla \cdot + (q) = 0$$

$$F :? \rightarrow ? \qquad \text{huss of 'gos} \qquad \text{electromagnities}$$

$$\int_{\mathcal{L}} \int_{\mathcal{L}} q + \int_{\mathcal{L}} \nabla \cdot + (q) = 0$$

## Wave Equation as a Conservation Law

Rewrite the wave equation in conservation law form:

$$C^{2} N^{ff} = (C N^{x})^{f} = C (N^{f})^{x} = C N^{x}$$

$$N^{f} = C N^{x}$$

$$N^{f} = C N^{x}$$

$$\ddot{q} = \begin{pmatrix} u \\ v \end{pmatrix} \qquad \ddot{\varphi} = \begin{pmatrix} v \\ v \end{pmatrix}_{\xi} = \begin{pmatrix}$$

# Solving Conservation Laws Solve

$$u_{t} = v_{x}$$

$$v_{t} = u_{x}.$$

$$A$$

$$q_{t} + c_{t} = 0$$

$$q_{t} + c_{t} = 0$$

$$q_{t} + v_{t} = 0$$

Demo: Hyperbolic PDE [cleared]

## Hyperbolic: Solution Properties

#### Properties of the solution for hyperbolic equations:

- have conserved quantities (e.g. energy, cf. HW1)
- For linear conservation laws, smoothness of IC+BC data determines smoothness of solution for all time (nonlinear, maybe not)
- Diagonalization of flux Jacobian yields characteristic speeds

#### Outline

#### Introduction

Notes Notes (unfilled, with empty boxes) About the Class Classification of PDEs

Preliminaries: Differencing

Interpolation Error Estimates (reference)

Finite Difference Methods for Time-Dependent Problems

Finite Volume Methods for Hyperbolic Conservation Laws

Finite Element Methods for Elliptic Problems

Discontinuous Galerkin Methods for Hyperbolic Problems

### Interpolation and Vandermonde Matrices

$$\{\mathbf{x}\_1,...,\mathbf{x}\_n\}$$
 
$$\{\mathbf{phi}\_1,...,\mathbf{phi}\_n\}$$
 
$$F(x_i) \approx \sum_{i=1}^N \alpha_i \phi_i(x_i) = p_{N-1}(x_i)$$
 
$$V_{ij} = (\phi_j(x_i))_{ij}$$
 
$$V\vec{\alpha} = f(\vec{x}) \Leftrightarrow \vec{\alpha} = V^{-1}f(\vec{x})$$
 
$$f'(x_i) \approx \sum_{i=1}^N \alpha_i \phi_i'(x_i) = p_{N-1}'(x_i) \qquad V'_{ij} = (\phi_j'(x_i))_{ij}$$
 
$$V'\vec{\alpha} = p_{N-1}(\vec{x}) \approx f'(\vec{x}) \qquad f'(\vec{x}) = V'V^{-1}f(\vec{x})$$

**Demo:** Taking Derivatives with Vandermonde Matrices [cleared]