

Fourier Transforms of Inverse Toeplitz Operators

Fourier transform $P_h^{-1} Q_h \mathbf{y}$?

$$\frac{\hat{q}(\theta)}{\hat{p}(\theta)} \hat{y}(\theta)$$

$$(\mathcal{T}_{\tilde{x}})_{j,k} = \sum_k t_{j-k} x_k \rightsquigarrow (\mathcal{T}_{\tilde{x}})^\wedge(\theta) = \hat{t}(\theta) \tilde{x}(\theta)$$

$$(\widehat{P_h Q_h \tilde{x}})(\theta) = \hat{p}(\theta) \hat{q}(\theta) \tilde{x}(\theta)$$

$$(\widehat{P_h^{-1} P_h Q_h \tilde{x}})(\theta) = \frac{1}{\hat{p}(\theta)} \hat{p}(\theta) \hat{q}(\theta) \tilde{x}(\theta) = \hat{q}(\theta) \tilde{x}(\theta)$$

Bounding the Operator Norm

Bound $\|P_h^{-1}Q_h\|_2^2$ using Fourier:

$$\begin{aligned} \|P_h^{-1}Q_h\|_2^2 &= \sup_{x \neq 0} \frac{\|P_h^{-1}Q_h x\|_2^2}{\|x\|_2^2} = \sup_{x \neq 0} \frac{\frac{h}{2\pi} \int_{-\pi}^{\pi} \left| \frac{\hat{q}(\theta)}{\hat{p}(\theta)} \hat{x}(\theta) \right|^2 d\theta}{\frac{h}{2\pi} \int_{-\pi}^{\pi} |\hat{x}(\theta)|^2 d\theta} \\ &\leq \sup_{x \neq 0} \frac{\max_{\varphi \in (-\pi, \pi)} \left| \frac{\hat{q}(\varphi)}{\hat{p}(\varphi)} \right|^2 \int_{-\pi}^{\pi} |\hat{x}(\theta)|^2 d\theta}{\int_{-\pi}^{\pi} |\hat{x}(\theta)|^2 d\theta} \\ &= \max_{\varphi \in (-\pi, \pi)} \left| \frac{\hat{q}(\varphi)}{\hat{p}(\varphi)} \right|^2 \end{aligned}$$

Analogously $\|P_h^{-1}\|_2^2 \leq \max_{\varphi \in (-\pi, \pi)} \left| \frac{1}{\hat{p}(\varphi)} \right|^2$.

Is the upper bound attained?

If $\hat{x}(\theta) = \delta(\theta - \varphi^*)$ where $|\hat{q}(\theta)/\hat{p}(\theta)|$ attains its max, then yes.
 $x_k = \frac{1}{2\pi} e^{i\varphi^* k}$

von Neumann Stability

Two-level finite difference scheme

$$P_h \mathbf{v}_{\ell+1} = Q_h \mathbf{v}_\ell + h_t \mathbf{b}_\ell,$$

where P_h and Q_h are Toeplitz operators with vectors \mathbf{p} and \mathbf{q} .

Definition (Symbol of a Two-Level Finite Difference Scheme)

Let

$$\hat{\mathbf{p}}(\theta) = \sum_k p_k e^{-i\varphi k}, \quad \hat{\mathbf{q}}(\theta) = \sum_k q_k e^{-i\varphi k}.$$

Then the **symbol** of the two-level FD method is $s(\varphi) = \hat{\mathbf{q}}(\varphi)/\hat{\mathbf{p}}(\varphi)$.

Definition (Von Neumann Stability)

If

$$\max_{\varphi} |s(\varphi)| \leq 1, \quad \max_{\varphi} \left| \frac{1}{\hat{\mathbf{p}}(\varphi)} \right| \leq c$$

for some constant $c > 0$, we say the scheme is **von Neumann stable**.

Comparison with Lax-Richtmyer Stability

Need $\|(P_h^{-1}Q_h)^{\ell}P_h^{-1}\| \leq c. \leftarrow$

\forall stab \Rightarrow Lax-Richtmyer stab \Rightarrow Lax stab.

Why is bounding the symbol the most salient part?

Often, if $\|P_h^{-1}Q_h\|$ has issues, so does $\|P_h^{-1}\|$.

Main restriction of von Neumann stability?

- Only works for infinite/periodic domains
- Have BCs? More difficult (\rightarrow strike words)

von Neumann Stability: ETBS (1/2)

$$0 < \lambda < 1$$

ETBS: Let $\lambda = ah_t/h_x$. $u_{k,l+1} = \lambda u_{k-1,l} + (1-\lambda)u_{k,l}$.

$$P_h = I \quad Q_h = \text{tridiag}(\lambda, 1-\lambda, 0)$$

Auxiliary result: FT of $r_k = \delta_{k,j}$

$$\rightarrow \hat{r}(\varphi) = \sum_k r_k e^{-i\varphi k} = \sum_k \delta_{k,j} e^{-i\varphi k} = e^{-i\varphi j}$$

$$(Q\vec{x})_j = \sum_k x_k q_{j-k} \rightarrow (Q\vec{x})_0 = x_0 q_0 + x_{-1} q_1 + x_1 q_{-1} + \dots$$

$$\vec{q} = (\dots, 0, \overset{\downarrow q_0}{1-\lambda}, \lambda, 0, \dots)$$

$$\hat{p}(\theta) = 1 \quad \hat{q}(\theta) = \lambda e^{-i\theta} + (1-\lambda) = 1 - \lambda(1 - e^{-i\theta})$$

$$|\hat{s}(\theta)|^2 = \left| \frac{\hat{q}(\theta)}{\hat{p}(\theta)} \right|^2 = (1 - \lambda(1 - e^{-i\theta})) (1 - \lambda(1 - e^{i\theta}))$$

$$= 1 + 2(\lambda - \lambda^2)(\cos\theta - 1).$$

von Neumann Stability: ETBS (2/2)

Found: $|s(\varphi)|^2 = 1 + 2(\lambda - \lambda^2)(\cos \varphi - 1)$.

Take derivative wrt φ

$$\frac{d}{d\varphi} (1 + 2(\lambda - \lambda^2)(\cos \varphi - 1)) = -2(\lambda - \lambda^2) \sin \varphi \stackrel{!}{=} 0$$

if only if $\varphi \in \mathbb{Z}\pi$

$$\text{Let } m \in \mathbb{Z}, \varphi = m\pi \quad s(m\pi) = 1 + 2(\lambda - \lambda^2)((-1)^m - 1)$$

For m even, $s(m\pi) = 1$.

$$\text{For } m \text{ odd, } s(m\pi) = 1 - 4(\lambda - \lambda^2) = (1 - 2\lambda)^2$$

So $|s(\varphi)|^2 \leq 1$ if only if

$$|1 - 2\lambda| \leq 1 \Leftrightarrow 0 \leq \lambda \leq 1$$

von Neumann Stability: ETCS

Let $\lambda = ah_t/h_x$. Then

$$u_{k,l+1} = \frac{\lambda}{2} u_{k-1,l} + u_{k,l} - \frac{\lambda}{2} u_{k+1,l}.$$

$P_n = I$ $Q_n = \text{tridiag}(\frac{\lambda}{2}, 1-\lambda, -\frac{\lambda}{2})$

So $\hat{p}(\theta) = 1$ and

$$\hat{q}(\theta) = \frac{\lambda}{2} e^{-i\varphi} + 1 - \frac{\lambda}{2} e^{-i\varphi}(-1) = 1 - \lambda \sin(\varphi)i$$

$$\max_{\varphi \in [-\pi, \pi]} |s(\varphi)|^2 = \left| \frac{\hat{q}(\varphi)}{\hat{p}(\varphi)} \right|^2 = 1 + \lambda^2 \sin^2(\varphi) \geq 1$$

ETCS is unstable.

von Neumann Stability: Crank-Nicolson

Let $\lambda = ah_t/(4h_x)$

$$-\lambda u_{k-1,l+1} + u_{k,l+1} + \lambda u_{k+1,l+1} = \lambda u_{k-1,l} + u_{k,l} - \lambda u_{k+1,l}$$

$$P_n = \text{tridiag}(-\lambda, 1, \lambda) \quad Q_n = \text{tridiag}(\lambda, 1, -\lambda)$$

$$\hat{p}(\varphi) = -\lambda e^{-i\varphi} + 1 + \lambda e^{i\varphi} = 1 + 2\lambda i \sin(\varphi)$$

$$\hat{q}(\varphi) = \lambda e^{-i\varphi} + 1 - \lambda e^{i\varphi} = 1 - 2\lambda i \sin(\varphi)$$

$$|s(\varphi)|^2 = \frac{1 + 4 \sin^2(\varphi)}{1 + 4 \sin^2(\varphi)} = 1$$

CN is unconditionally stable.

Outline

Introduction

Finite Difference Methods for Time-Dependent Problems

1D Advection

Stability and Convergence

Von Neumann Stability

Dispersion and Dissipation

A Glimpse of Parabolic PDEs

Finite Volume Methods for Hyperbolic Conservation Laws

Finite Element Methods for Elliptic Problems

Discontinuous Galerkin Methods for Hyperbolic Problems

Studying Solutions of the PDE

$$\frac{d}{dx} (e^{\lambda x}) = \lambda (e^{\lambda x})$$

Saw numerically: interesting dispersion/dissipation behavior.

Want: theoretical understanding.

Consider *linear, continuous* (not yet discrete) differential operators

$$L_1 u = u_t + a u_x,$$

$$L_2 u = u_t - \underbrace{D u_{xx}} + \underbrace{a u_x} \quad (D > 0)$$

$$L_3 u = \underbrace{u_t + a u_x} - \underbrace{\mu u_{xxx}}.$$

What could we use as a prototype solution?

A Prototype Solution of the PDE

Observation: all these operators are diagonalized by complex exponentials. Come up with a 'prototype complex exponential solution'.

$$e^{i(kx - \omega t)}$$

What type of function is this?

Wave-like Solutions of the PDE

$$z(x, t) = z_0 e^{i(kx - \omega t)}$$

Observations in connection with L ?

What is the **dispersion relation**?