$$\begin{split} \vec{h}_{t+1} &= \vec{h}_{t} + h L \left( \vec{h}_{t} \right) \quad c \rightarrow f \in \\ HL \Rightarrow \quad TV(\vec{h}_{t+1}) < TV(\vec{h}_{t}) \in \\ SSP \quad meltods \quad ore \quad conv. \quad conb. \quad of \quad FE slyps \\ SSP \quad meltods \quad ore \quad conv. \quad conb. \quad of \quad FE slyps \\ \vec{h}_{t} &= \begin{pmatrix} \partial_{x} & \partial_{y} & \partial_{y} \\ \partial_{y} & U \end{pmatrix} \\ \int U & U \\ \int U & U \\ \in E_{x} \quad \vec{h}_{t} + \nabla \cdot f(\vec{h}) = 0 \\ f & H \\ i \in H, \\ f & H \\ f & H \\ i \in H, \\ f & H \\ f & H \\ i \in H, \\ f & H \\ f$$

### Systems of Conservation Laws

Linear system of hyperbolic conservation laws,  $A \in \mathbb{R}^{m \times m}$ :

$$u_{t} + Au_{x} = 0,$$

$$u(x,0) = u_{0}(x).$$
Assumptions on A?
$$A = A + i, \quad \text{oly}(\lambda_{1}, \dots, \lambda_{m})$$

$$H = \lambda_{p} \hat{r}_{p} \quad \text{oly}(\lambda_{1}, \dots, \lambda_{m})$$

$$H = \lambda_{p} \hat{r}_{p$$

Linear System Solution

$$\boldsymbol{v} = R^{-1}\boldsymbol{u}, \qquad \boldsymbol{v}_t + \Lambda \boldsymbol{v}_x = 0.$$



Write down the solution.

$$W(x_{1}t) = \sum_{p} \vec{r_{p}} \quad \underbrace{V_{p}(x_{-}\lambda_{p}t, 0)}_{\vec{v}}$$

$$\vec{V}(x_{1}0) = \mathbb{R}^{-1} \quad \vec{v}(x_{1}0)$$

What is the impact on boundary conditions? E.g.  $(\lambda_p) = (-c, 0, c)$  for a BC at x = 0 for [0, 1]?

### Characteristics for Systems (1/2)

Consider system  $\boldsymbol{u}_t + \boldsymbol{f}(\boldsymbol{u})_x = 0$ . Write in quasilinear form:

$$\tilde{U}_{e} + \int f(u) \tilde{U}_{x} = 0$$

When hyperbolic?

Characteristics for Systems (2/2)What about characteristics/shock speeds? - By considering char, decomp., can shill define characteristils. In characteristics through oardpt. - No longer on ODE For char. curves. Are values of  $\boldsymbol{u}$  still constant along characteristics? No, only char. coofficients are " Socally constant"

#### Shocks and Riemann Problems for Systems

$$u_t + Au_x = 0,$$
  
$$u(x,0) = \begin{cases} u_l & x < 0, \\ u_r & x > 0. \end{cases}$$

( $u_r \quad x > 0.$ Solution? (Assume strict hyperbolicity with  $\lambda_1 < \lambda_2 < \cdots < \lambda_m$ .)

$$\vec{u}_{g} = \sum_{p} \phi_{p} \vec{v}_{p} \qquad \vec{u}_{r} = \sum_{p} \beta_{p} \vec{v}_{p} \qquad \Rightarrow \forall_{p} (x_{1} 0) = \begin{cases} \alpha_{p} \times \alpha_{0} \\ \beta_{p} \times p \end{cases}$$

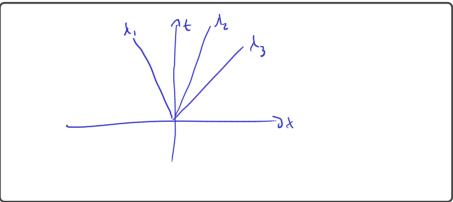
$$(el P(x_{1}) bc \quad the max, value of p so that x - \lambda_{p} t > 0$$

$$\vec{u}_{1}(x_{1}) = \sum_{p=1}^{p(x_{1})} \beta_{p} \vec{v}_{p} + \sum_{p=P(x_{1}t)+i}^{m} \alpha_{p} \vec{v}_{p}$$

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# Shock Fans (1/2)

What does the solution look like?



Jump across the characteristic associated with  $\lambda_p$ ?

$$\begin{bmatrix} \vec{u} \end{bmatrix} = \begin{pmatrix} p & -d \\ p & -d \end{pmatrix} \vec{r}_{p}$$

# Shock Fans (2/2)

Do those jumps satisfy Rankine-Hugoniot?

$$\begin{bmatrix} \vec{f} \end{bmatrix} = A \begin{bmatrix} \vec{n} \end{bmatrix} = \left( \frac{\beta_{p} \cdot \alpha_{p}}{A r_{p}} - \frac{\beta_{p} \cdot \alpha_{p}}{A r_{p}} \right) \lambda \vec{r_{p}}$$

$$= \lambda_{p} \begin{bmatrix} \vec{n} \end{bmatrix}$$

How can we find intermediate values of  $\boldsymbol{u}$ ?

**Two Dimensions** 

 $u_t + f(u)_x + g(u)_y = 0$ . Finite volume methods generalize in principle:

$$\frac{d\pi_{ij}}{dt} + \frac{1}{n^2} \int_{y_{i-\frac{1}{2}}}^{y_{i+\frac{1}{2}}} \int (u(x_{i+\frac{1}{2}}, y, t)) - \int (u(x_{i+\frac{1}{2}}, y, t)) dy$$

$$+ \frac{1}{n^2} \int_{y_{i-\frac{1}{2}}}^{x_{i+\frac{1}{2}}} (analogous) dx$$

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However:

Introduction

Finite Difference Methods for Time-Dependent Problems

Finite Volume Methods for Hyperbolic Conservation Laws

Finite Element Methods for Elliptic Problems

tl;dr: Functional Analysis Back to Elliptic PDEs Galerkin Approximation Finite Elements: A 1D Cartoon Finite Elements in 2D Approximation Theory in Sobolev Spaces Saddle Point Problems, Stokes, and Mixed FEM Non-symmetric Bilinear Forms

Discontinuous Galerkin Methods for Hyperbolic Problems