

Weak Derivatives

Define the space L^1_{loc} of **locally integrable functions**.

$$L^1_{\text{loc}} = \{ u : (u : \Omega \rightarrow \mathbb{R}) \text{ measurable} \}$$

$$\int |u(x) \varphi(x)| dx < \infty \text{ for all } \varphi \in C_0^\infty(\Omega) \}$$

Definition (Weak Derivative)

$v \in L^1_{\text{loc}}(\Omega)$ is the **weak partial derivative** of $u \in L^1_{\text{loc}}(\Omega)$ of multi-index order k if

$$\int v \varphi dx = (-1)^{|k|} \int u D^k \varphi dx \quad \text{for all } \varphi \in C_0^\infty(\Omega)$$

Handwritten annotations: $D^k u$ with an arrow pointing to v ; $D^k u$ with an arrow pointing to u .

In this case $D^k u := v$

Weak Derivatives: Examples (1/2)

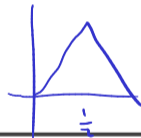
Consider all these on the interval $[-1, 1]$.

$$4x - 4x^2$$

$$f_1(x) = 4(1-x)x$$

$$4 - 8x$$

$$f_2(x) = \begin{cases} 2x & x \leq 1/2, \\ 2 - 2x & x > 1/2. \end{cases}$$



$$D_w f_2 = \begin{cases} 2 & x < 1/2 \\ -2 & x > 1/2 \end{cases}$$

Weak Derivatives: Examples (2/2)

$$f_3(x) = \sqrt{\frac{1}{2}} - \sqrt{|x - 1/2|}$$

$$D_w f_3 = \begin{cases} \frac{1}{2\sqrt{1/2-x}} & x < \frac{1}{2} \\ -\frac{1}{2\sqrt{x-1/2}} & x > \frac{1}{2} \end{cases}$$

Sobolev Spaces

Let $\Omega \subset \mathbb{R}^n$, $k \in \mathbb{N}_0$ and $1 \leq p < \infty$.

Definition ((k, p)-Sobolev Norm/Space)

Sobolev norm

$$\|u\|_{k,p} = \sqrt[p]{\sum_{|\vec{\alpha}| \leq k} \|D_{\vec{\alpha}} u\|_p^p}$$

Sobolev

seminorm

$$|u|_{k,p} = \sqrt[p]{\sum_{|\vec{\alpha}| = k} \|D_{\vec{\alpha}} u\|_p^p}$$

$$W^{k,p} = \{u : \Omega \rightarrow \mathbb{R}, \|u\|_{k,p} < \infty\}$$

More Sobolev Spaces

$W^{0,2}?$

C^2 \xrightarrow{Suv}

$W^{s,2}?$

$H^s \rightarrow$ Hilbert spaces $(u,v)_{H^s} = \sum_{|k| \leq s} (D_{u,k}, D_{v,k})_{L^2}$

$H_0^1(\Omega)?$

Closure of $C_0^\infty(\Omega)$ under $\|\cdot\|_{1,2}$.
"zero on the boundary"

Outline

Introduction

Finite Difference Methods for Time-Dependent Problems

Finite Volume Methods for Hyperbolic Conservation Laws

Finite Element Methods for Elliptic Problems

tl;dr: Functional Analysis

Back to Elliptic PDEs

Galerkin Approximation

Finite Elements: A 1D Cartoon

Finite Elements in 2D

Approximation Theory in Sobolev Spaces

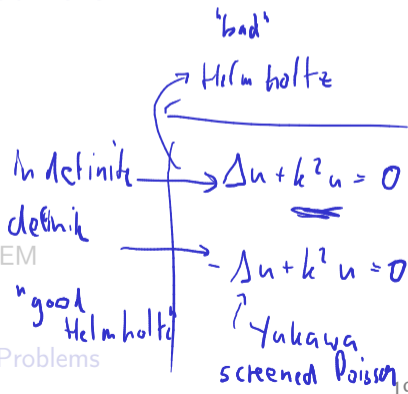
Saddle Point Problems, Stokes, and Mixed FEM

Non-symmetric Bilinear Forms

Discontinuous Galerkin Methods for Hyperbolic Problems

$$u(x,t) = U(x) e^{i\omega t}$$

$$\partial_t^2 u = \Delta u$$



An Elliptic Model Problem $\Delta = \operatorname{div} \operatorname{grad} u$

Let $\Omega \subset \mathbb{R}^n$ open, bounded, $f \in H^1(\Omega)$.

$$-\nabla \cdot \nabla u + u = f(x) \quad (x \in \Omega),$$

$$u(x) = 0 \quad (x \in \partial\Omega).$$

"Poisson eqn"
 $-\Delta u = f$

Let $V := H_0^1(\Omega)$. Integration by parts? (Gauss's theorem applied to $a\mathbf{b}$):

$$\int_{\Omega} \nabla a \cdot \mathbf{b} + \int_{\Omega} a \nabla \cdot \mathbf{b} = \int_{\Omega} \nabla \cdot (a\mathbf{b}) - \int_{\partial\Omega} \hat{n} \cdot (a\mathbf{b})$$

Weak form?

$$\int_{\Omega} -\nabla \cdot \nabla u v + \int_{\Omega} u v = \int_{\Omega} f v \quad v \in H_0^1$$

$$b = \nabla u$$

$$a = v$$

$$\int_{\Omega} \nabla u \cdot \nabla v - \underbrace{\int_{\partial\Omega} \hat{n} \cdot (v \nabla u)}_{=0} + \int_{\Omega} u v = \int_{\Omega} f v$$

Motivation: Bilinear Forms and Functionals

$$\int_{\Omega} \nabla u \cdot \nabla v + \int_{\Omega} uv = \int_{\Omega} fv. \quad V = H_0^1$$

(Note: A blue arrow points from the handwritten $(u, v)_{H^1}$ to the first two terms of the equation.)

This is the **weak form** of the strong-form problem. The task is to find a $u \in V$ that satisfies this for all test functions $v \in V$.

Recast this in terms of bilinear forms and functionals:

$$a(u, v) = (\nabla u, \nabla v)_{L^2} + (u, v)_{L^2}$$

$$g(v) = (f, v)_{L^2}$$

Want $u \in V$: $a(u, v) = g(v)$ for all $v \in V$

Dual Spaces and Functionals

$$g(\alpha v + \beta w) = \alpha g(v) + \beta g(w)$$

Bounded Linear Functional

Let $(V, \|\cdot\|)$ be a Banach space. A **linear functional** is a linear function $g : V \rightarrow \mathbb{R}$. It is **bounded** (\Leftrightarrow continuous) if there exists a constant C so that $|g(v)| \leq C \|v\|$ for all $v \in V$.

Dual Space

Let $(V, \|\cdot\|)$ be a Banach space. Then the **dual space** V' is the space of bounded linear functionals on V .

Dual Space is Banach (cf. e.g. Trèves 1967)

V' is a Banach space with the **dual norm**

$$\|g\|_{V'} = \sup_{v \in V \setminus \{0\}} \frac{|g(v)|}{\|v\|_V}$$

Functionals in the Model Problem

Is g from the model problem a bounded functional? (In what space?)

$$\begin{aligned} \|g\|_{V'} &= \sup_{v \in H' \setminus \{0\}} \frac{(f, v)_{L^2}}{\|v\|_{H'}} \stackrel{c-s}{\leq} \frac{\|f\|_{L^2} \|v\|_{L^2}}{\|v\|_{L^2} + \|D_u v\|_{L^2}} \\ &\leq \frac{\|f\|_{L^2} \cancel{\|v\|_{L^2}}}{\cancel{\|v\|_{L^2}}} \end{aligned}$$

That bound felt loose and wasteful. Can we do better?

$$\begin{aligned} \|f\|_{H^{-1}} &= \sup_{v \in H' \setminus \{0\}} \frac{(f, v)_{L^2}}{\|v\|_{H'}} \\ |g(v)| &\leq \|f\|_{H^{-1}} \|v\|_{H'} \end{aligned}$$

Riesz Representation Theorem (1/3)

Let V be a Hilbert space with inner product $\langle \cdot, \cdot \rangle$.

Theorem (Riesz)

Let g be a bounded linear functional on V , i.e. $g \in V'$. Then there exists a unique $u \in V$ so that $g(v) = \langle u, v \rangle$ for all $v \in V$.

Let $g \in V'$. $N(\cdot)$: "null space"

Case I: $N(g) = V$. Pick $u = 0$, done.

Case II: $N(g) \neq V$. Let $w \in N(g)^\perp \setminus \{0\}$. $g(w) = \alpha \neq 0$

$$g\left(\frac{g(v)}{\alpha} w\right) = \frac{g(v)}{g(w)} \cdot g(w) = g(v)$$

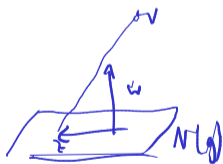
Let $v \in V$. Let $z := v - (g(v)/\alpha) w$. $g(z) = 0 \Leftrightarrow z \in N(g)$.
 $\Rightarrow z \perp w \Leftrightarrow (z, v) = 0$.

Riesz Representation Theorem: Proof (2/3)

Have $w \in N(g)^\perp \setminus \{0\}$, $\alpha = g(w) \neq 0$, and $z := v - (g(v)/\alpha)w \perp w$.

$$0 = (z, w) \Leftrightarrow \left(\frac{g(v)}{\alpha} w, w \right) = (v, w) \quad \text{for all } v$$

Multiply by $\frac{\alpha}{(w, w)}$



$$g(v) = \frac{\alpha}{(w, w)} \left(\frac{g(v)}{\alpha} w, w \right) = (v, w) \frac{\alpha}{(w, w)}$$

$$= \left(v, \underbrace{\frac{\alpha}{(w, w)} w}_{u :=} \right)$$

Riesz Representation Theorem: Proof (3/3)

Uniqueness of u ?

$$\text{Suppose } \bar{u} \quad : \quad g(v) = (u, v) = (\bar{u}, v)$$

$$\Leftrightarrow (u - \bar{u}, v) = 0 \quad \forall v \quad \left. \vphantom{\forall v} \right\} \text{Pick: } v = u - \bar{u}$$

$$\Rightarrow (u - \bar{u}, u - \bar{u}) = 0 = \|u - \bar{u}\|^2 \Rightarrow u = \bar{u}$$

Back to the Model Problem

$$a(u, v) = \langle \nabla u, \nabla v \rangle_{L^2} + \langle u, v \rangle_{L^2}$$

$$g(v) = \langle f, v \rangle_{L^2}$$

$$a(u, v) = g(v)$$

Have we learned anything about the solvability of this problem?

