

What's still to do?

L^2 Estimates

Let *H* be a Hilbert space with the norm $\|\cdot\|_H$ and the inner product $\langle \cdot, \cdot \rangle$. (Think: $H = L^2$, $V = H^1$.)

Theorem (Aubin-Nitsche)

Let $V \subseteq H'$ be a subspace that becomes a Hilbert space under the norm $\|\cdot\|_{V}$. Let the embedding $V \to H$ be continuous. Then we have for the finite element solution $u \in V_h \subset V$:

$$\| u - u_n \|_{H} \leq c_{1} \| u - u_{1} \|_{V} \cdot \sup_{g \in H \setminus H} \left(\frac{1}{\|g\|_{H}} \inf_{g \in V_{h}} \|g_{g} - v_{h} \|_{V} \right)$$

if with every $g \in H$ we associate the unique (weak) solution φ_g of the equation (also called the dual problem)

prinul
$$\rightarrow a(u, v) = g(v)$$
 $\forall v$
dual $\rightarrow a(u, t_g) - (g, v)$ $\forall w$ as corr, back to BV P? 22

Aubin-Nitsche: Proof_

$$\begin{pmatrix} \|w\|_{H}^{2} = \sup_{g \in H \setminus \{0\}} \frac{(j_{1}w)}{\|g\|_{H}} & hu \text{ for } w = n \cdot h_{1} \\ (g_{1}w - w_{n}) \stackrel{A...A}{=} = \alpha (n - n_{n-1}v_{g}) \stackrel{Go}{=} = \alpha (u - w_{n-1}v_{g} - v_{n}) \\ \in c_{1} |\|w - w_{n}\|_{V} |\|vg - v_{n}|_{V} \\ (g_{1}w - u_{n}) \in c_{1} |\|w - u_{n}\|_{V} \quad i_{n}f |\|p_{j} - v_{n}\|_{V} \\ (g_{1}w - u_{n}) \in c_{1} |\|w - u_{n}\|_{V} \quad i_{n}f |\|p_{j} - v_{n}\|_{V} \\ \|w - u_{n}\|_{H} = \sup_{g \in H} \frac{(g_{1}w - h_{1})}{\|g\|_{H}} \in c_{1} |\|w - u_{n}\|_{V} \quad \sup_{g \in H} \left(\frac{1}{\|g\|_{H}} - \frac{i_{n}f}{v_{n}eV_{n}}\right)$$

L^2 Estimates using Aubin-Nitsche

So does Aubin-Nitsche give us an L^2 estimate?

24

Introduction

Finite Difference Methods for Time-Dependent Problems

Finite Volume Methods for Hyperbolic Conservation Laws

Finite Element Methods for Elliptic Problems

tl;dr: Functional Analysis Back to Elliptic PDEs Galerkin Approximation Finite Elements: A 1D Cartoon Finite Elements in 2D Approximation Theory in Sobolev Spaces Saddle Point Problems, Stokes, and Mixed FEM Non-symmetric Bilinear Forms

Discontinuous Galerkin Methods for Hyperbolic Problems

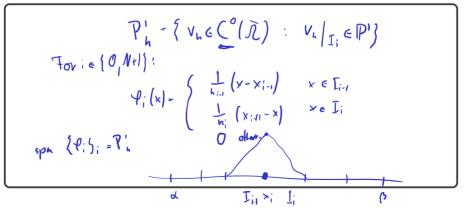
Finite Elements in 1D: Discrete Form

$$\begin{split} \Omega &:= [\alpha, \beta]. \text{ Look for } u \in H_0^1(\Omega) \text{, so that } a(u, \varphi) = \langle f, \varphi \rangle \text{ for all } \\ \varphi \in H_0^1(\Omega). \text{ Choose } \underbrace{V_h = \text{span}\{\varphi_1, \dots, \varphi_n\}}_{u_h} \text{ and expand } \\ u_h &= \sum_{i=1}^n \underbrace{u_h^i}_{i} \varphi_i \in V_h. \text{ Find the discrete system.} \end{split}$$

$$\begin{aligned} & \alpha \left(L_{h} | V_{h} \right) = \left(\frac{1}{2} | V_{h} \right) & \forall V_{h} \\ & \alpha \left(\sum_{i=1}^{L} u_{i}^{i} \forall i_{i} | V_{h} \right) = \left(\frac{1}{2} | I_{h} \right) & \forall V_{h} \end{aligned}$$

Grids and Hats
Let
$$I_i := [\alpha_i, \beta_i]$$
, so that $\overline{\Omega} = \bigcup_{i=0}^{N} I_i$ and $I_i^{\circ} \cap I_j = \emptyset$ for $i \neq j$. Consider a grid
 $\alpha = x_0^{\downarrow} < \cdots < x_N < x_{N+1} = \beta$,

i.e. $\alpha_i = x_i$, $\beta_i = x_{i+1}$ for $i \in \{0, ..., N\}$. The $\{x_i\}$ are called nodes of the grid. $h_i := x_{i+1} - x_i$ for $i \in \{0, ..., N\}$ and $h := \max_i h_i$. V_h ? Basis?



228

Degrees of Freedom and Matrices

Define something more general than basis coefficients to solve for.

$$y_{ii} : C(\tilde{X}) \rightarrow \mathcal{R} \qquad \forall \mapsto \forall (Y_i) \in \mathbb{R}$$

$$g | obal degrees of freedom$$

$$span \left\{ Y_i \right\} = \left(P'_n \right)^{1}$$

$$dual space of$$

Define shape functions and assemble the stiffness matrix:

Shape functions
$$\hat{\varphi}_i := \hat{\gamma}_i(\hat{\varphi}_j) = \hat{d}_{i,j}$$
 for $i, j \in \{0, \dots, M_i\}$
 $a(u_i, v_i) = f_i v_i$
 $(\hat{\varphi}_i, \hat{\varphi}_i) = a(u_{i,1}, \hat{\varphi}_i) = \sum_{j=1}^{N} \hat{\gamma}_j(u_j) a(\hat{\varphi}_j, \hat{\varphi}_j)$ $(i = 1 \dots N)$
 $u_i khows j matrix$

229

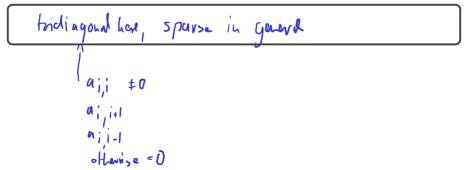
A Matrix Property for Efficiency

230

$$\alpha(u,v) = \int u'v'$$

$$(A_h)_{i,j} = a(\hat{arphi}_j, \hat{arphi}_i).$$

Anything special about the matrix?



Error Estimation

According to Céa, what's our main missing piece in error estimation now?

$$\begin{split} I_{h}^{1} : C^{\circ}(\bar{\mathcal{X}}) \to P'_{L} \\ v \mapsto \mathcal{E}_{i=0}^{n+1} \chi_{i}(v) \, \hat{\varphi}_{i} \in P'_{L} \end{split}$$

Interpolation Error (1D-only) For $v \in H^2(\Omega)$,

$$\| v - J_{h}^{1} v \|_{U} < h^{2} \|v\|_{H^{2}}$$
$$\| v - J_{h}^{2} v \|_{H^{2}} < h^{2} \|v\|_{H^{2}}$$

If $v \in H^1(\Omega) \setminus H^2(\Omega)$,

$$\| v - \overline{J}_{h}^{2} v \|_{L^{2}} \leq h \| v |_{H^{1}}$$
$$\| v - \overline{J}_{h}^{2} v \|_{H^{1}} \longrightarrow 0 \qquad (h \Rightarrow 0)$$

Is I_h^1 defined for $v \in H^2$? for $v \in H^1 \setminus H^2$?

Interpolation Error: Towards an Estimate

$$\alpha(u_n, v_n) = \left(f_1 v_n \right)$$

Provide an a-priori estimate.

$$\| u - u_h \|_{H^1} \in \frac{C_1}{C_0} \inf_{u \in P_h^1} \| u - v_h \|_{H^1} \in \frac{C_1}{C_0} \| u - I_h^1 u \|_{H^1} \in \frac{C_1}{C_0} \| u \|_{H^2}$$

What's the relationship between $I_h^1 u$ and u_h ?

Not the some!

Local-to-Global: Math refore ace coords

Construct a polynomial basis using this approach.

$$\begin{aligned}
\hat{\psi}_{\theta}(x') &= 1 - \hat{x} \\
\hat{\psi}_{i}(x) &= \hat{x} \\
\text{To got a basis of } P'(I_{i}): \\
& \quad \forall_{i}(x) = \begin{cases} \hat{\psi}_{i} \circ T_{i}^{-1}(x) & x \in [x_{i+1}, x_{i}] \\
& \quad \psi_{0} \circ T_{i}^{-1}(x) & x \in [x_{i}, x_{i+1}] \\
& \quad \eta \text{ lobul coards}
\end{aligned}$$

Demo: Developing FEM in 1D [cleared]

•

•