

$$u_{j, l+1} = G(u_{j-p, l}, \dots, u_{j+p, l})$$

'monotonic'    ↑    ↑    ↑  
 (LTF) is    ✓

# Monotone Schemes: Properties

## Theorem (Good properties of monotone schemes)

- ▶ *Local maximum principle:*

$$\min_{i \in \text{stencil around } j} u_i \leq G(u)_j \leq \max_{i \in \text{stencil around } j} u_i.$$

- ▶  *$L^1$ -contraction:*

$$\|G(u) - G(v)\|_{L^1} \leq \|u - v\|_{L^1}.$$

- ▶ *TVD:*

$$TV(G(u)) \leq TV(u).$$

- ▶ *Solutions to monotone schemes satisfy all entropy conditions.*

# Godunov's Theorem

## Theorem (Godunov)

*Monotone schemes are at most first-order accurate.*

What now?

Relax the cond? Just TVD?

# Linear Schemes

## Definition (Linear Schemes)

A scheme is called a **linear scheme** if it is linear when applied to a linear PDE:

$$u_t + au_x = 0,$$

where  $a$  is a constant.

Write the general case of a linear scheme for  $u_t + u_x = 0$ :

$$u_{j,l+1} = \sum_{k=-K}^K c_k(\lambda) u_{j-k,l} + G(\dots)$$

monotone  $\Leftrightarrow$  all  $c_k(\lambda) \geq 0$

$\hookrightarrow$  linear + monotone  $\Leftrightarrow$  "positive"

Linear + TVD = ?

## Theorem (TVD for linear Schemes)

*For linear schemes, TVD  $\Rightarrow$  monotone.*

What does that mean?

Linear, TVD  $\Rightarrow$  first order. boo!

Now what?

Try for nonlinear schemes ... ?

Need to prove TVD ...

$$TV(\vec{u}^l) = \sum_j |u_{j+1,e} - u_{j,e}|$$

$\uparrow$   
 $|\Delta_t u_{j,e}|$

## Harten's Lemma

### Theorem (Harten's Lemma)

If a scheme can be written as

$$\bar{u}_{j,\ell+1} = \bar{u}_{j,\ell} + \lambda(C_{j+1/2}\Delta_+ \bar{u}_j - D_{j-1/2}\Delta_- \bar{u}_j)$$

with  $C_{j+1/2} \geq 0$ ,  $D_{j+1/2} \geq 0$ ,  $1 - \lambda(C_{j+1/2} + D_{j+1/2}) \geq 0$  and  $\lambda = h_t/h_x$ , then it is TVD.

As a matter of notation, we have

$$\Delta_+ u_j = u_{j+1} - u_j,$$

$$\Delta_- u_j = u_j - u_{j-1}.$$

We have omitted the time subscript for the time level  $\ell$ .

# Harten's Lemma: Proof

$$\begin{aligned}
 \Delta_+ u_{j,e+1} &= \Delta_+ u_{j,e} + \lambda \Delta_+ (C_{j+\frac{1}{2}} \Delta_+ u_j - D_{j-\frac{1}{2}} \Delta_- u_j) \\
 &= \Delta_+ u_j + \lambda (C_{j+\frac{3}{2}} \Delta_+ u_{j+1} - D_{j-\frac{1}{2}} \Delta_- u_{j+1} \cancel{\Delta_+ u_j} \\
 &\quad - C_{j+\frac{1}{2}} \Delta_+ u_j + D_{j-\frac{1}{2}} \Delta_- u_j) \\
 &= (1 - \lambda (C_{j+\frac{1}{2}} + D_{j-\frac{1}{2}})) \Delta_+ u_j \\
 &\quad + \lambda C_{j+\frac{3}{2}} \Delta_+ u_{j+1} + \lambda D_{j-\frac{1}{2}} \Delta_- u_j
 \end{aligned}$$

$$\begin{aligned}
 |\Delta_+ u_{j,e+1}| &\leq \underbrace{(1 - \lambda (C_{j+\frac{1}{2}} + D_{j-\frac{1}{2}}))}_{\varepsilon_j} |\Delta_+ u_j| \\
 &\quad + \underbrace{\lambda C_{j+\frac{3}{2}}}_{\varepsilon_j} |\Delta_+ u_{j+1}| + \lambda \underbrace{D_{j-\frac{1}{2}}}_{\varepsilon_j} |\Delta_- u_j| \\
 &\quad + \underbrace{\lambda C_{j+\frac{1}{2}}}_{\varepsilon_j} |\Delta_+ u_j| + \underbrace{\lambda D_{j-\frac{1}{2}}}_{\varepsilon_j} |\Delta_+ u_j|
 \end{aligned}$$

$TV(\bar{u}^{e+1})$

$$\begin{aligned}
 \sum_j |\Delta_+ u_{j,e+1}| &\leq \sum_j (1 - \lambda (C_{j+\frac{1}{2}} + D_{j-\frac{1}{2}}) + \lambda C_{j+\frac{1}{2}} + \lambda D_{j-\frac{1}{2}}) |\Delta_+ u_j| \\
 &= TV(\bar{u}^e)
 \end{aligned}$$

# Minmod Scheme

Still assume  $f'(u) \geq 0$ .

$$f_{j+1/2}^{*,(1)} = f\left(\bar{u}_j + \underbrace{\frac{1}{2}(\bar{u}_{j+1} - \bar{u}_j)}_{\tilde{u}_j^{(1)}}\right), \quad f_{j+1/2}^{*,(2)} = f\left(\bar{u}_j + \underbrace{\frac{1}{2}(\bar{u}_j - \bar{u}_{j-1})}_{\tilde{u}_j^{(2)}}\right).$$

central
upwind

Design a 'safe' thing to use for  $\tilde{u}$ :

$$\text{minmod}(a, b) = \begin{cases} a & |a| < |b|, ab > 0 \\ b & |b| \leq |a|, ab > 0 \\ 0 & ab \leq 0 \end{cases} \quad \tilde{u}_j = \text{minmod}(\tilde{u}_j^{(1)}, \tilde{u}_j^{(2)})$$

↑
↑
  
 slopes

"slope limiter"

$f_{j+1/2}^{*,(1)} = f(\bar{u}_j + \tilde{u}_j)$

Local extremum which drives TVD growth



## Minmod is TVD

Show that Minmod is TVD:

✓