

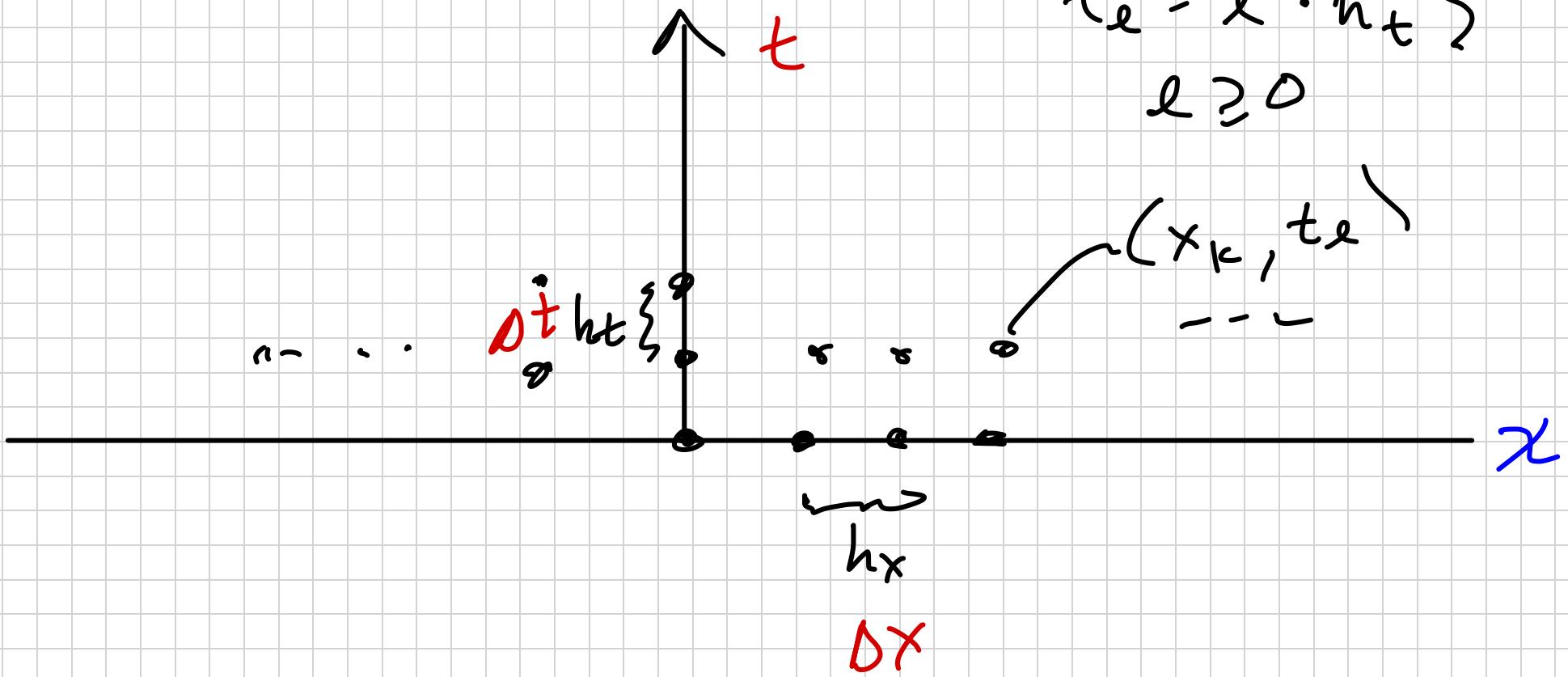
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Top 2: FD for time dep problems

Objectives

- ① Introduce explicit methods
implicit methods
- ② Develop a 2-level scheme
- ③ Say something about error

Grid: $\{(x_k, t_e) : x_k = k \cdot h_x$
 $t_e = e \cdot h_t\}$
 $e \geq 0$



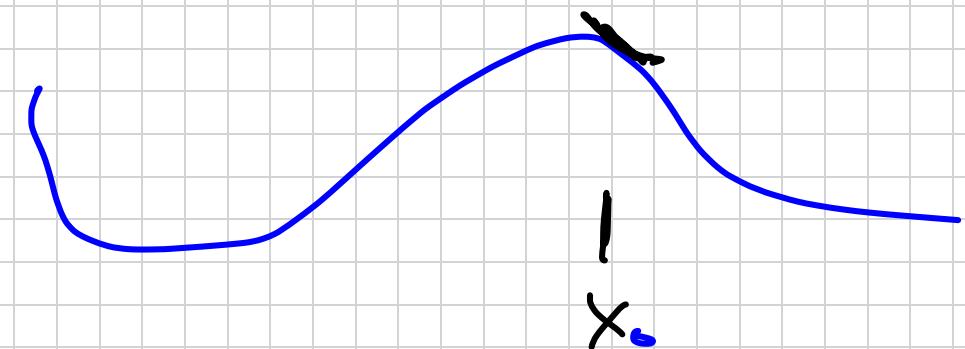
advection

$$\begin{cases} u_t + c u_x = 0 \\ u(x, 0) = u_0(x) \end{cases}$$

→ need to approximate derivatives

Consider

$$f(x)$$



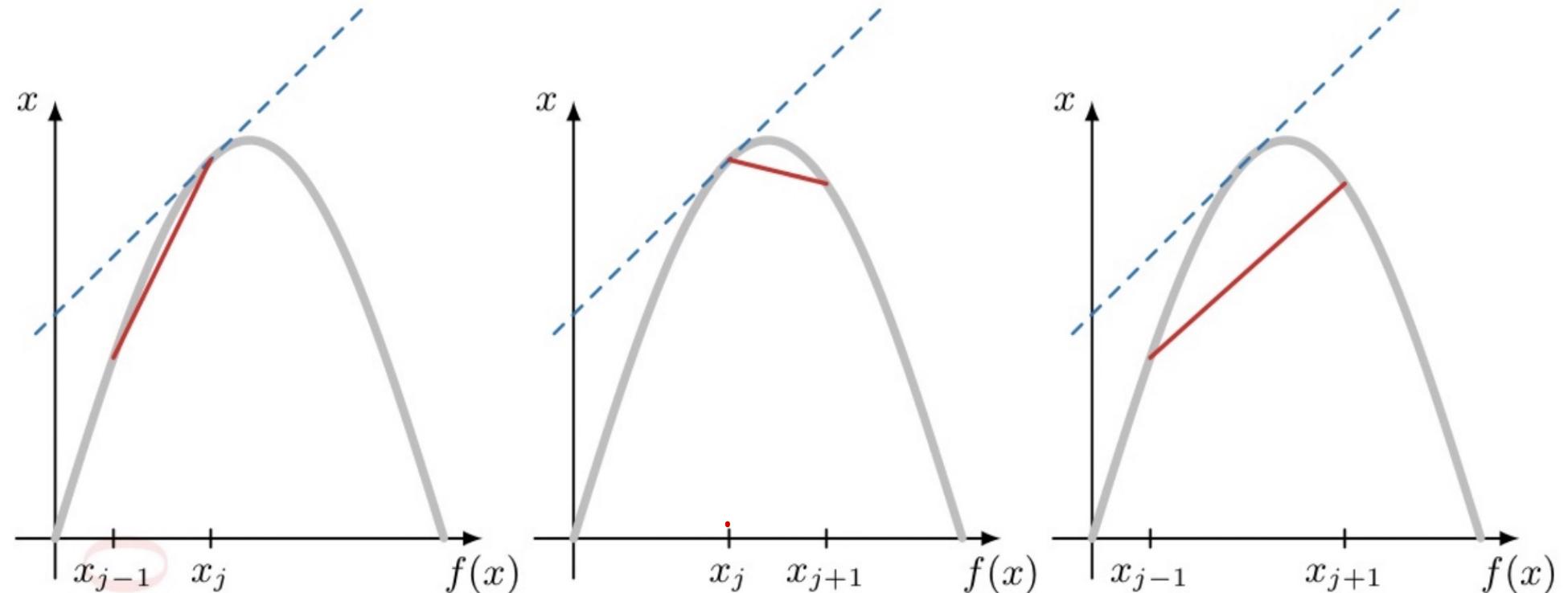
Taylor:

$$f(x_0 + h_x) = f(x_0) + f'(x_0) h_x + f''(3) \frac{h_x^2}{2}$$

$$\Rightarrow f'(x_0) = \frac{f(x_0 + h_x) - f(x_0)}{h_x}$$

"forward diff"

$f''(3) \frac{h_x^2}{2}$
"1st order"



Back

Fwd

Central

$$f(x_0 + h_x) = \cancel{f(x_0)} + f'(x_0)h_x + \frac{f''(x_0)h_x^2}{2} + \frac{f'''(z^+)h_x^3}{6}$$

$$f(x_0 - h_x) = \cancel{f(x_0)} - f'(x_0)h_x + \frac{f''(x_0)h_x^2}{2} - \frac{f'''(z^-)h_x^3}{6}$$

$$\frac{f(x_0 + h_x) - f(x_0 - h_x)}{2h_x} = f'(x_0) + \frac{f'''(z^+)h_x^2}{12} + \frac{f'''(z^-)h_x^2}{12}$$

"central"

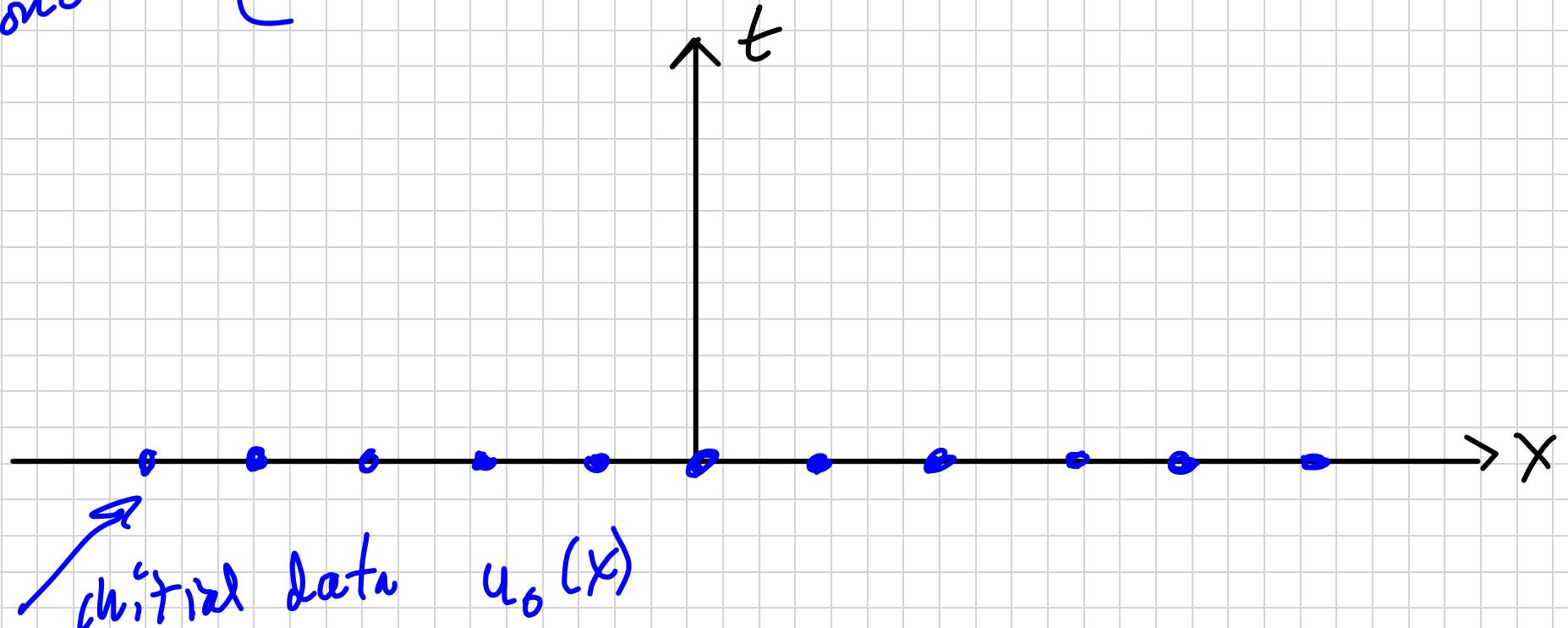
$$O(h_x^2)$$

"2nd order"

$$u_t + a u_x = 0 \quad a > 0$$

advection with initial condition

$$\left\{ \begin{array}{l} \frac{\partial u(x,t)}{\partial t} + a \frac{\partial u(x,t)}{\partial x} = 0 \\ u(x,0) = u_0(x) \end{array} \right.$$



$$\frac{\partial u(x, t)}{\partial t} + \alpha$$

$$\frac{\partial u(x, t)}{\partial x} = 0$$

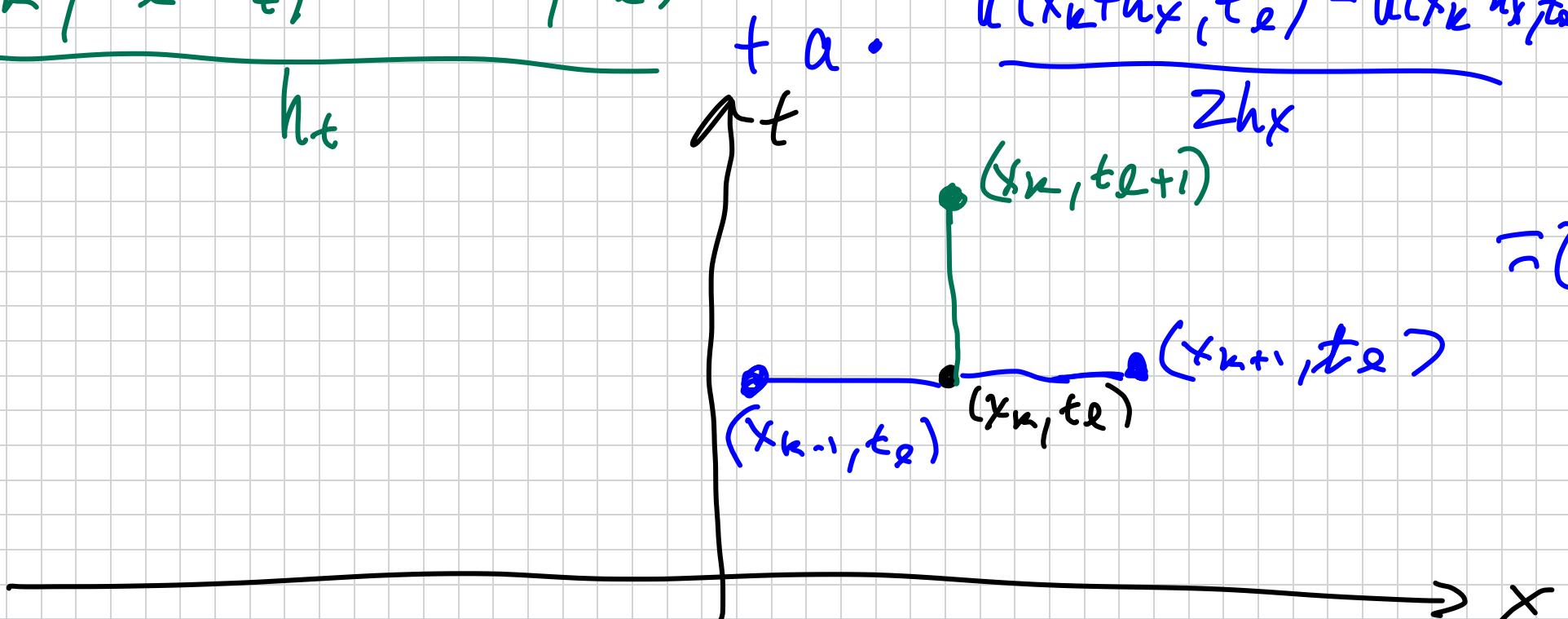
$$u(1) = u(0)$$

Fwd differencing
in time
at $x = x_k$

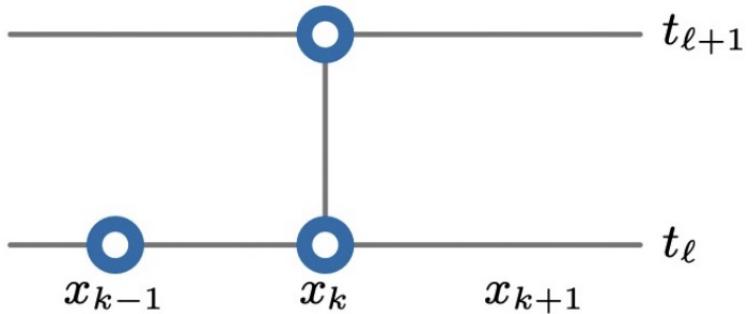
Central differencing
in space
at time t_e

$$\frac{u(x_k, t_e + h_t) - u(x_k, t_e)}{h_t} + \alpha \cdot$$

$$\frac{u(x_{k+h_x}, t_e) - u(x_{k-h_x}, t_e)}{2h_x} = 0$$

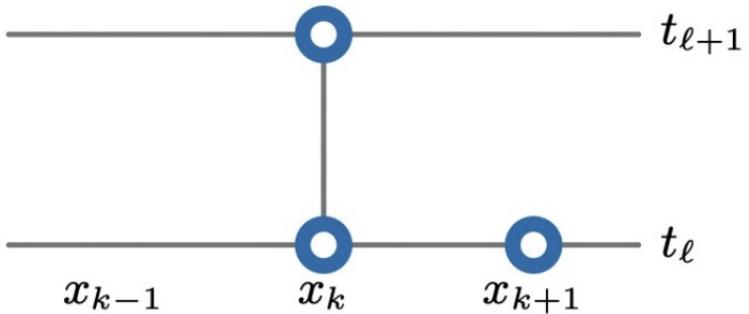


$$\frac{u_{k,\ell+1} - u_{k,\ell}}{h_t} + a \frac{u_{k,\ell} - u_{k-1,\ell}}{h_x} = 0$$



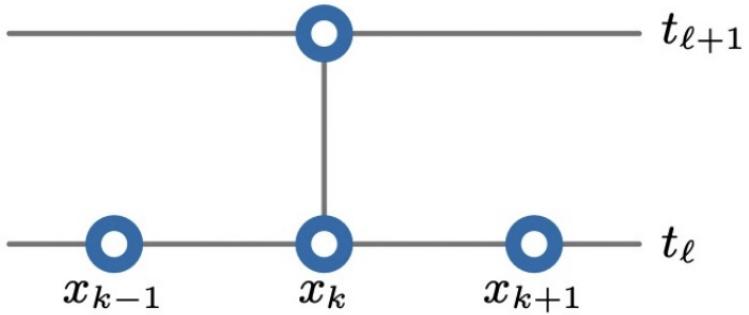
a. Explicit time, backward space (ETBS)

$$\frac{u_{k,\ell+1} - u_{k,\ell}}{h_t} + a \frac{u_{k+1,\ell} - u_{k,\ell}}{h_x} = 0$$



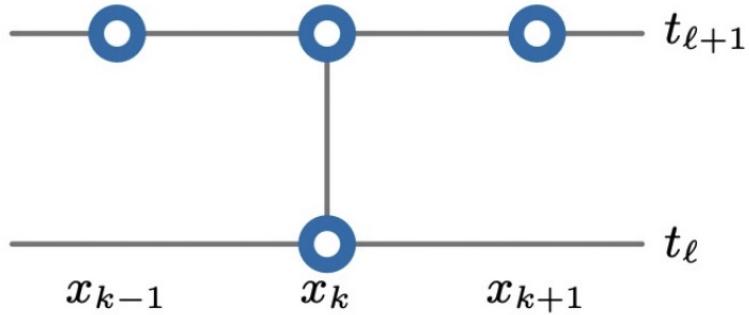
b. Explicit time, forward space (ETFS)

$$\frac{u_{k,\ell+1} - u_{k,\ell}}{h_t} + a \frac{u_{k+1,\ell} - u_{k-1,\ell}}{2h_x} = 0$$



c. Explicit time, centered space (ETCS)

$$\frac{u_{k,\ell+1} - u_{k,\ell}}{h_t} + a \frac{u_{k+1,\ell+1} - u_{k-1,\ell+1}}{2h_x} = 0$$



d. Implicit time, centered space (ITCS)

ETBS

$$\frac{u_{k,e+1} - u_{k,e}}{h_t} + a \cdot \frac{u_{k,e} - u_{k-1,e}}{hx} = 0$$

$$\rightarrow u_{k,e+1} - u_{k,e} + \frac{ah_t}{hx} (u_{k,e} - u_{k-1,e}) = 0$$

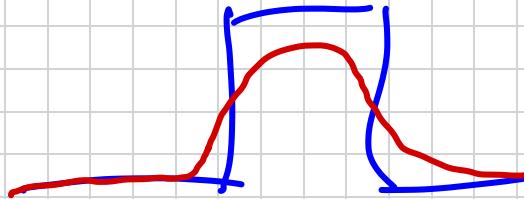
$$\begin{aligned} \rightarrow u_{k,e+1} &= u_{k,e} - \frac{ah_t}{hx} (u_{k,e} - u_{k-1,e}) \\ &= u_{k,e} - \lambda (u_{k,e} - u_{k-1,e}) \end{aligned}$$

$\bullet x_{k,t+1}$

$$\begin{aligned} J &= \begin{bmatrix} 1 & 0 & 0 & \dots & 0 & \dots & \dots & 0 \\ 0 & 2 & 1 & \dots & x_k & \dots & \dots & x_{x-1} \\ 0 & 1 & 2 & \dots & \dots & \dots & \dots & 0 \end{bmatrix} \\ J &= \begin{bmatrix} 1 & 0 & 0 & \dots & 0 & \dots & \dots & 0 \\ 0 & 2 & 1 & \dots & x_k & \dots & \dots & x_{x-1} \\ 0 & 1 & 2 & \dots & \dots & \dots & \dots & 0 \end{bmatrix} \\ J_{-1} &= \begin{bmatrix} 0 & 1 & 2 & \dots & x_{x-2} \end{bmatrix} \end{aligned}$$

Open Questions

- ① why does the profile "smooth"
- ② " get smaller?
- ③ Is it traveling at the correct speed?
- ④ Is the approximation accurate?
in terms of h_x, h_ϵ
- ⑤ Why does the approx. "blow up" with
 $\lambda > 1$?



TODO: read Remark 5.2
Terminology for FD stencils.

$$\text{let } \underline{u}_e = \begin{bmatrix} \vdots \\ u_{-1,e} \\ u_0,e \\ u_1,e \\ \vdots \end{bmatrix}$$

$$\text{let } e_{x,e} = u(x_k, t_e) - u_{k,e}$$

\uparrow

exact solution to

$$u_t + \alpha u_x = 0$$

at (x_k, t_e)

\uparrow

approximation to
 $u(x, t)$ at (x_k, t_e)

$$\Rightarrow \text{look at } \underline{e}_e = \underline{U}_e - \underline{u}_e$$

\uparrow

\uparrow

exact vector approximation

Definition 5.7: Two-Level Linear Finite-Difference Scheme

A finite-difference scheme that can be written as,

$$P_h \mathbf{u}_{\ell+1} = Q_h \mathbf{u}_\ell + h_t \mathbf{b}_\ell, \quad (5.5)$$

is called a two-level linear finite-difference scheme. Each iteration depends only on two instances of time. Examples are given in Example 5.8.