

Today 2/5

① Quantify dispersion
and
dissipation

② Introduce "conservation laws"

Last time

$$\text{let } z(x,t) = z_0 e^{i(kx - \omega t)}$$

$$\text{solve } Lu = 0$$

(e.g. $L = \partial_t + a \partial_x$)

$$\text{with } \omega(k) = \alpha(k) + i\beta(k)$$

if $\beta < 0 \rightarrow$ dissipation

if $\alpha(k) =$ nonlinear in k

\rightarrow dispersive

(if $\alpha(k) = c \cdot k$
then non dispersive)

$$\left(v_{ph} = \frac{\alpha(k)}{k} = \text{phase velocity} \right)$$

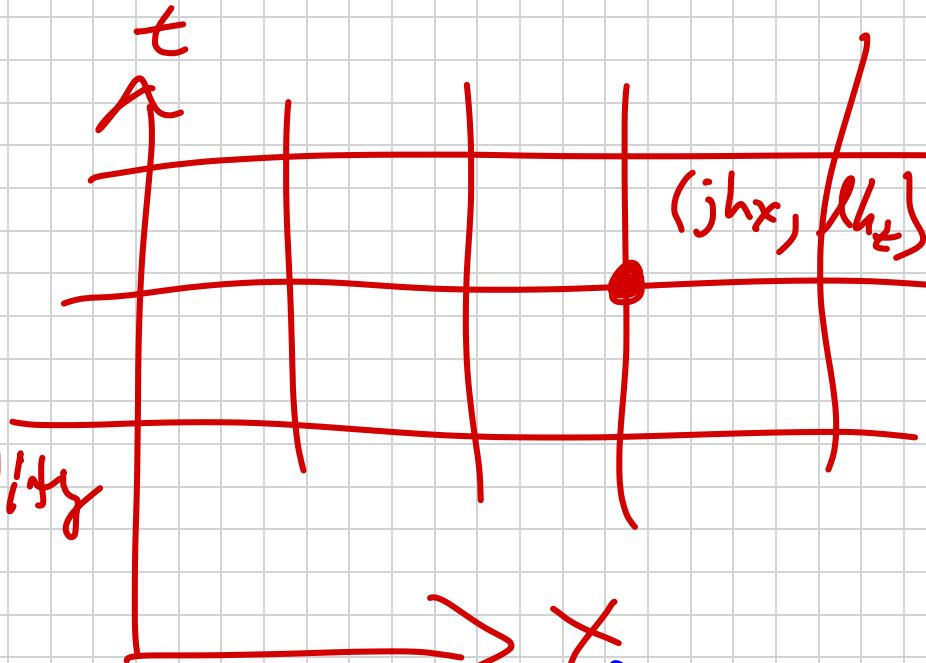
So what about our method?

$$\text{let } z_{je} = z_0 e^{i(k_j h_x - \omega_l h_t)}$$

look at FTBS

$$u_{j,t+1} = \gamma u_{j+1,t} + (1-\gamma) u_{j,t}$$

need $\gamma = \frac{a h_t}{h_x} < 1$ for stability



$$\begin{aligned} \Rightarrow z_0 e^{i(k_j h_x - \omega(l+1)h_t)} &= \gamma z_0 e^{i(k(j+1)h_x - \omega l h_t)} \\ &\quad + (1-\gamma) z_0 e^{i(k_j h_x - \omega l h_t)} \\ \Rightarrow e^{-\omega h_t} &= \gamma e^{-i k h_x} + (1-\gamma) \end{aligned}$$

$$e^{-i\omega h t} = \gamma e^{-i k h x} + 1 - \gamma$$



the "symbol" $s(k h x)$
or the amplification factor

What is " ω " for this numerical scheme?

$$e^{-i\omega h t} = s$$

let $s = \text{complex}$

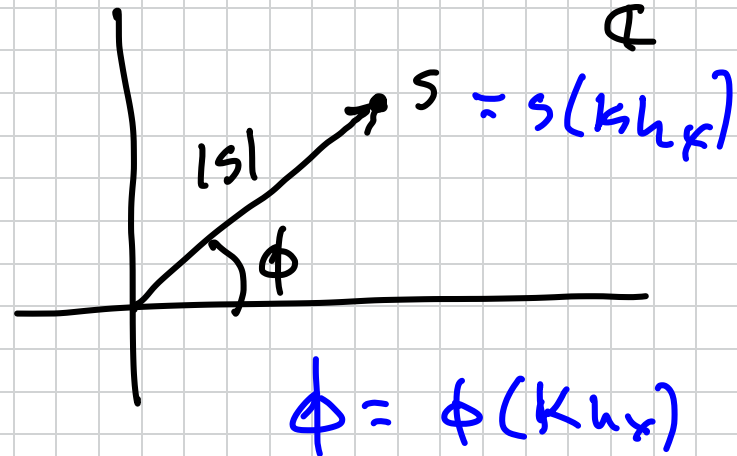
$$= |s| e^{i\phi}$$

$$= e^{\ln|s| + i\phi}$$

$$\Rightarrow -i\omega h t = \ln|s| + i\phi$$

$$\Rightarrow \omega = \frac{i \ln|s| - \phi}{h t}$$

for some ϕ



$$\begin{aligned}
 \omega &= \frac{i \ln|s| - \phi}{h_t} \\
 z_{j\ell} &= z_0 e^{i(k_j h_x - \omega \ell h_t)} \\
 &= z_0 e^{i(k_j h_x - \frac{i \ln|s| - \phi}{h_t} \ell h_t)} \\
 &= z_0 e^{\ln|s| \ell} e^{i(k_j h_x - (\frac{-\phi}{h_t}) \ell h_t)} \\
 &= z_0 e^{\ln|s| \ell} e^{i(k_j h_x - (\frac{-\phi}{h_t}) \ell h_t)} \\
 &= z_0 |s|^\ell e^{i(k_j h_x - (\frac{-\phi}{h_t}) \ell h_t)}
 \end{aligned}$$

if $|s| < 1$ Then dissipative

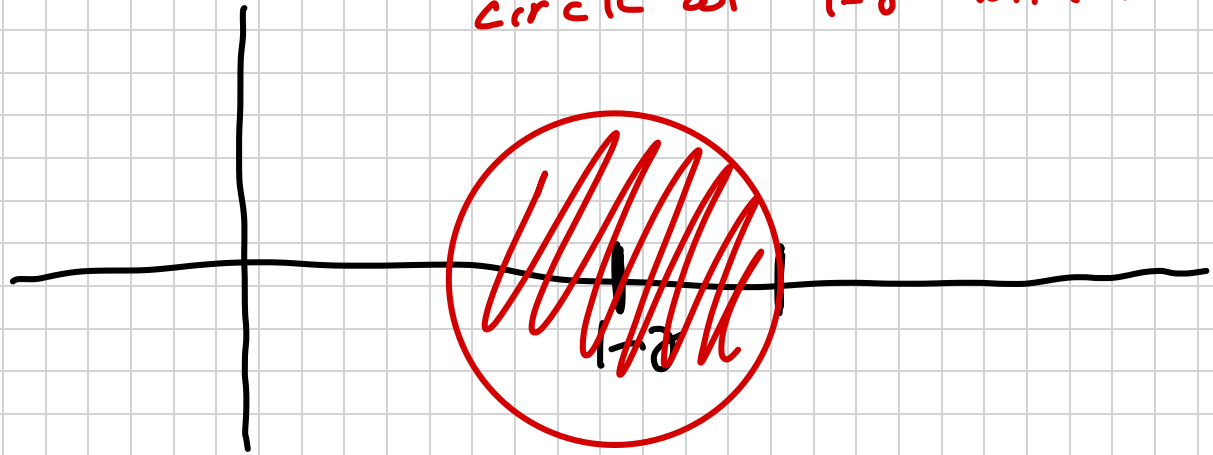
if $\frac{-\phi}{h_t}$ nonlinear in k ,
then dispersive.

ETBS

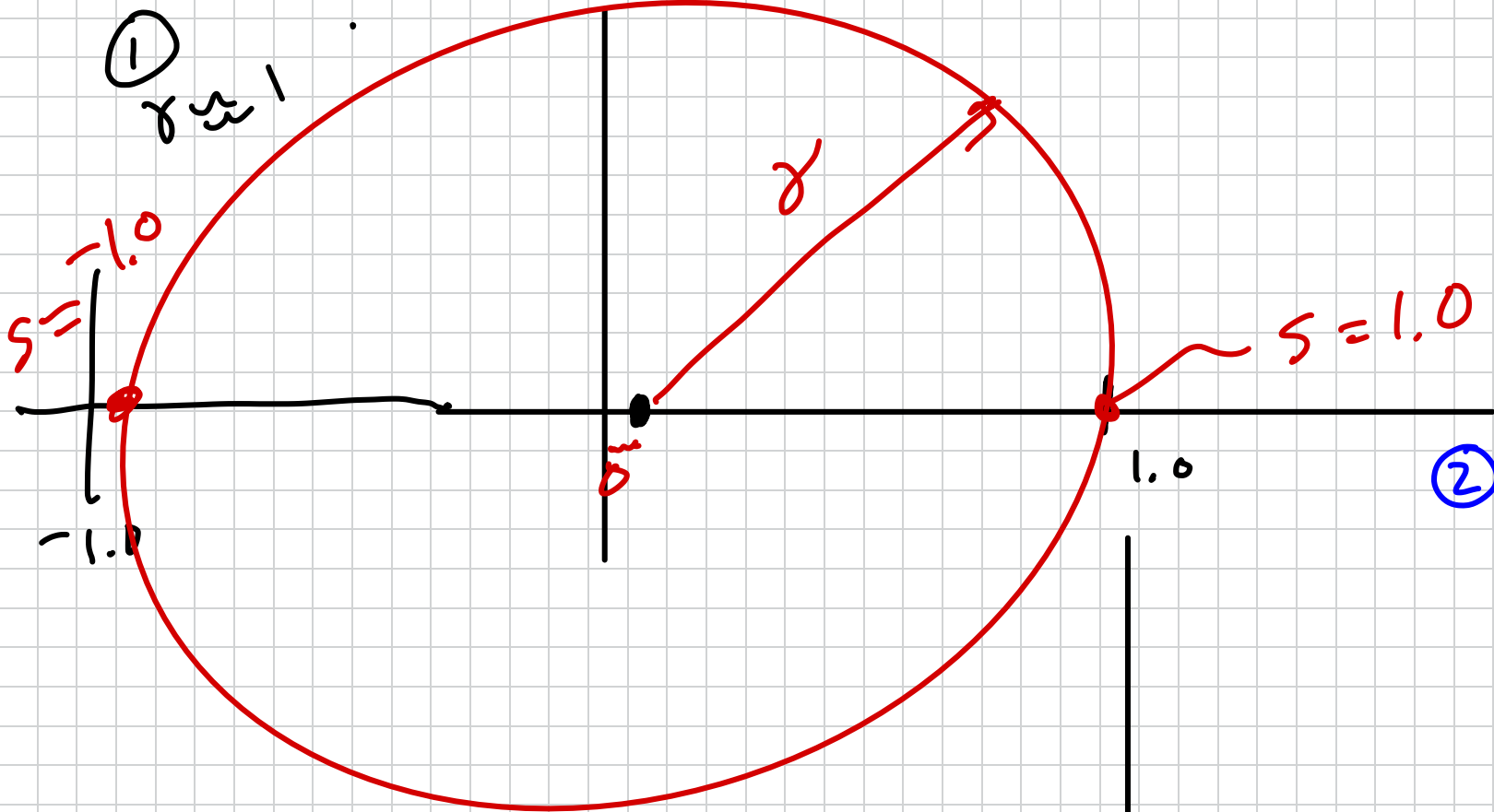
$$e^{-i\omega h t} = S(kh x) \\ = 1 - \gamma + \gamma e^{-i k h x}$$

circle at $1 - \gamma$ with radius γ

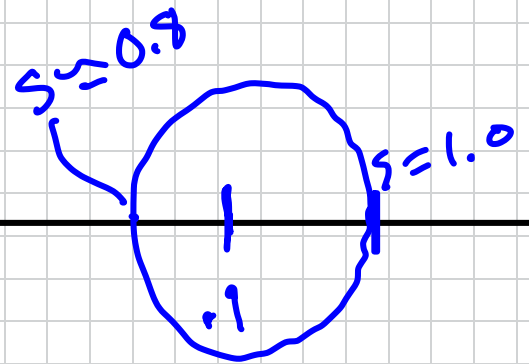
$$\gamma = a \frac{h t}{h x}$$



$$\zeta = 1 - \gamma + \gamma e^{-i k h x}$$



② $\gamma \ll 1$
 $\gamma = 0.1$



$$s(kh_x) = 1 - \gamma + \gamma e^{-ikh_x}$$

if $kh_x \approx$ small

$$\text{then } e^{-ikh_x} \approx 1 - ikh_x$$

$$\Rightarrow s \approx 1 - \gamma + \gamma - \gamma ikh_x \\ = 1 - \gamma ikh_x$$

$$\text{Return to } e^{-i\omega t} = s$$

$$\Rightarrow \cos \omega t - i \sin \omega t \approx 1 - \gamma ikh_x$$

if $\omega t \approx$ small

$$1 - i\omega t \approx 1 - \gamma ikh_x$$

$$\Rightarrow \omega \approx \gamma k \frac{h_x}{h_t} = a k$$

$$u_t + a u_x = 0$$

what about non-constant a ?

what if this is nonlinear?

what if we have more than a single scalar variable? (Euler)

what about 2D? 3D?

A conservation law is of the form

$$\frac{\partial}{\partial t} u + \frac{\partial f(u)}{\partial x} = 0$$

If f is differentiable

Then $u_t + f'(u) u_x = 0$

In 2D or 3D:

$$\frac{\partial u}{\partial t} + \nabla_{\underline{x}} \cdot \underline{f}(u) = 0$$

Example

$$u_t + y u_x - x u_y = 0$$

Conservative form?

$$u_t + \nabla \cdot (\quad) = 0 \quad ?$$

hint: $\nabla \cdot (\underline{b} u) = \underline{b} \cdot \nabla u + (\nabla \cdot \underline{b}) u$

$$u_t + [y, -x]^T \cdot \nabla u \quad \nabla \cdot \begin{bmatrix} y \\ -x \end{bmatrix} = 0$$

$$\Rightarrow u_t + \nabla \cdot \left(\begin{bmatrix} y \\ -x \end{bmatrix} u \right) = 0$$

①

conservative form

$$u_t + \partial_x (f(u)) = 0$$

advection:

$$u_t + \partial_x (a u) = 0$$

non conservative form:

$$u_t + f'(u) \partial_x u = 0$$

advection

$$u_t + a \partial_x u = 0$$

Example

$$u_t + x u_x = 0$$

(2D)

$$u_t + \nabla \cdot (\underline{f}(u)) = 0$$

$$u_t + [\partial_x, \partial_y] \cdot [f_1(u), f_2(u)] = 0$$

(17)

$$u_t + \partial_x(f(u)) = 0$$

Case $f(u) = \frac{u^2}{2}$

Burger's eq.

$$u_t + \partial_x\left(\frac{u^2}{2}\right) = 0$$

or

$$u_t + u u_x = 0$$

Consider any curve $x(t)$
that satisfies $x'(t) = u(x(t), t)$

$$x(0) = u(x(0), 0)$$

$$\frac{d u(x(t), t)}{dt} = \frac{\partial (u(x(t), t))}{\partial t} + \frac{dx(t)}{dt} \cdot \frac{\partial u(x(t), t)}{\partial x}$$

$$= u_t + x'(t) u_x = 0$$

Curves given by

$$\frac{dx}{dt} = u \leftarrow \text{an initial cond}$$

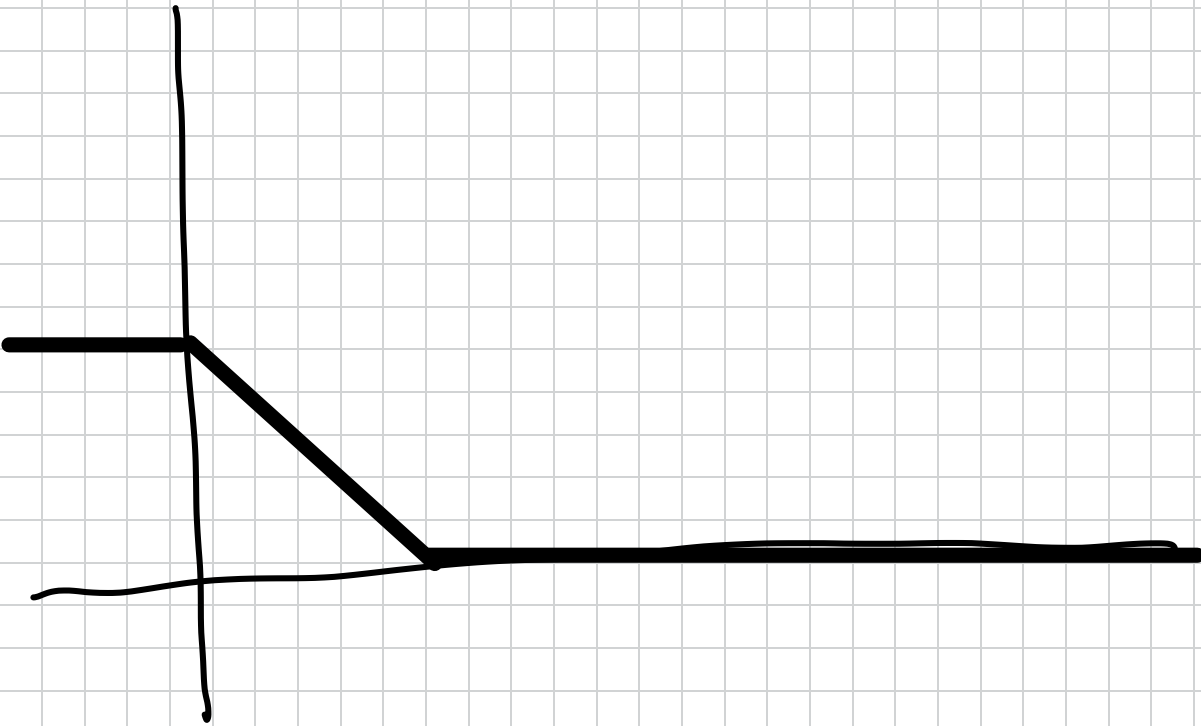
→ straight lines that depend on $u(x, 0)$

Case 1

$$u_t + uu_x = 0$$

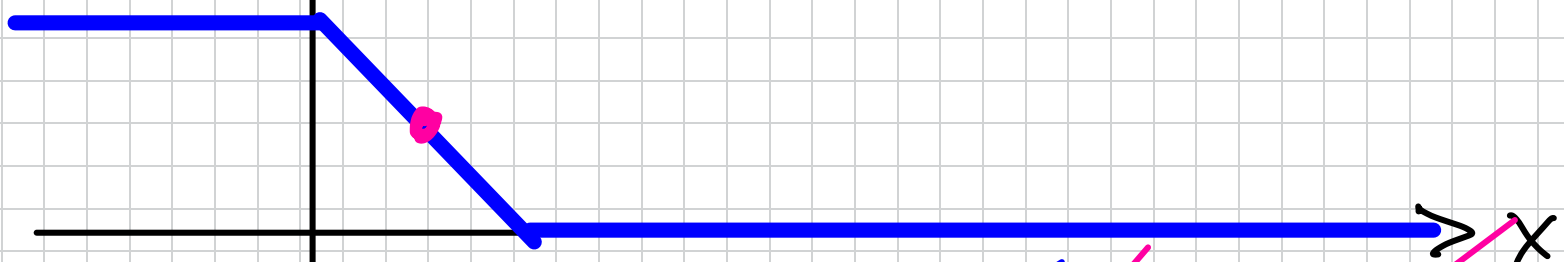
$$u(x, 0) =$$

$$\begin{cases} 1 & x \leq 0 \\ 1-x & x \in [0, 1] \\ 0 & x > 1 \end{cases}$$



u

$u(x,0)$



t

$\frac{dx}{dt} = u(x,0)$

