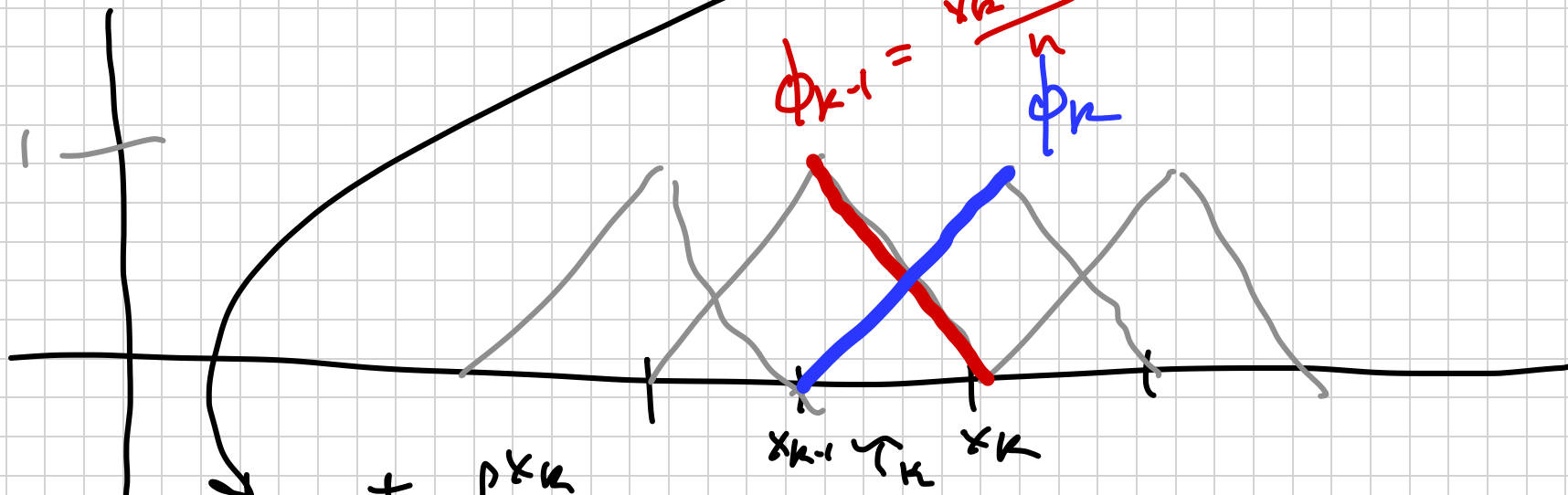


How to handle $\int_0^1 f(x) \phi_j(x) dx$



hand $\int_{x_{k-1}}^{x_k} f(x) \cdot \phi_i dx$

change of variables:

let $t = \frac{x - x_{k-1}}{h} \Rightarrow t = 0 \dots 1$
 $\Rightarrow x = x_{k-1} + ht$
 $dx = h dt$

$\int_0^1 f(x_{k-1} + ht) \cdot \phi_{k-1}(x_{k-1} + ht) \cdot h dt$

$\phi_{k-1} = \frac{x_k - x}{h} = \frac{x_k - x_{k-1} - ht}{h}$
 $= 1 - t$

$$\int_0^1 f(x_{k-1} + ht) \cdot (1-t) h dt$$

midpoint rule (1pt Gauss Quadrature)

$$\text{let } t_{\text{mid}} = 0.5$$

$$\text{width} = 1.0$$

$$\hat{a} \quad f(x_{k-1} + h \cdot t_{\text{mid}}) \cdot (1 - t_{\text{mid}}) \cdot h$$

We have

$$-\partial_x (k(x) \partial_x u) = f$$

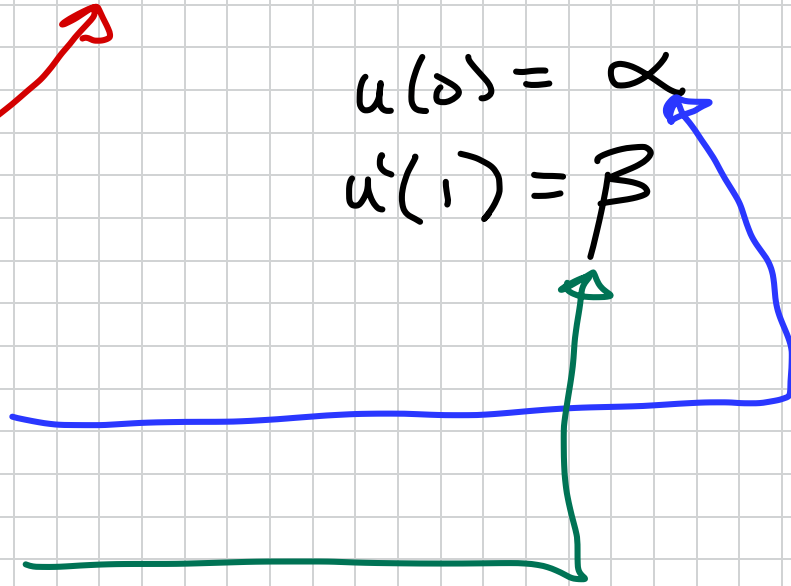
$$u(0) = \alpha$$

$$u'(1) = \beta$$

① $k(x) > 0$?

② $\alpha \neq 0$

③ $\beta \neq 0$



① $k(x) > 0$:

$$-\partial_x (k(x) \partial_x u) = f$$

$$\rightarrow \int_0^1 -\partial_x (k(x) \partial_x u) v \, dx = \int_0^1 f v \, dx$$

I.B.P. $\rightarrow \int_0^1 k(x) \partial_x u \partial_x v - k(x) \partial_x u v \Big|_0^1 = \int_0^1 f v$

how to compute? ↑ details

want $\int_{x_{n-1}}^{x_n} k(x) \phi_i'(x) \phi_j'(x) \, dx$

$$\phi_i = \frac{x_{k-1} - x}{x_{i-1} - x_{k-1}}$$

$$\int_{x_{n-1}}^{x_n} k(x) \cdot \left(\pm \frac{1}{h}\right) \left(\pm \frac{1}{h}\right) \, dx$$

$$\rightarrow \phi_i' = \pm \frac{1}{h}$$

change:

$$x = x_{n-1} + ht$$
$$dx = h \, dt$$

$$\int_0^1 k(x_{n-1} + ht) \cdot \underbrace{\pm \frac{1}{h}}_{h} \cdot h \, dt$$

② $\alpha \neq 0$

$$-u_{xx} = f$$

$$u(0) = \alpha$$

$$u'(0) = 0$$

Weak form:

find $u \in V$ st.

$$\int_0^1 -u_{xx} v \, dx = \int_0^1 f v$$

$$\rightarrow \int_0^1 u_x v_x \, dx - u_x v \Big|_0^1 = \int_0^1 f v \, dx$$

$\forall v \in V$.

$$V = \left\{ v \in L^2 \mid \begin{array}{l} a(v, v) < \infty \\ v(0) = 0 \end{array} \right\}$$

find $u \in V$ s.t.

$$a(u, v) = \langle f, v \rangle \quad \forall v \in V.$$

Another view: find u that minimizes

$$J(u) = \frac{1}{2} a(u, u) - \langle f, u \rangle$$

Is this the same?

$$J'(u)[v]$$

↑

$$= \lim_{\varepsilon \rightarrow 0} \frac{J(u + \varepsilon v) - J(u)}{\varepsilon}$$

"derivative J in the direction v "

$$= \lim_{\varepsilon \rightarrow 0} \frac{\frac{1}{2} a(u + \varepsilon v, u + \varepsilon v) - \langle f, u + \varepsilon v \rangle - \frac{1}{2} a(u, u) + \langle f, u \rangle}{\varepsilon}$$

$$= \lim_{\varepsilon \rightarrow 0} \frac{\cancel{\frac{1}{2} a(u, u)} + \varepsilon a(u, u) + \frac{1}{2} \varepsilon^2 a(u, u) - \cancel{\frac{1}{2} a(u, u)} - \varepsilon \langle f, v \rangle}{\varepsilon}$$

$$= a(u, u) - \langle f, u \rangle$$

u satisfies

$$J(u) \leq J(u + \varepsilon v) \quad \forall \begin{matrix} u + \varepsilon v \\ \in \left\{ v \mid v(0) = \alpha \right\} \end{matrix}$$

Take away:

Find $u \in \left\{ v \in L^2 \mid \begin{matrix} a(u, v) < \infty \\ u(0) = \alpha \end{matrix} \right\}$

$$\int_0^1 u_x v_x dx = \int_0^1 f v dx$$

for all $v \in \left\{ v \in L^2 \mid \begin{matrix} a(v, v) < \infty \\ v(0) = 0 \end{matrix} \right\}$

Alternative view:

$$-u_{xx} = f$$

$$u(0) = \alpha$$

$$u'(1) = \beta$$

$$\text{let } u_0(x) \in C^2$$

$$\text{let } u_0(0) = \alpha$$

$$\text{Now let } w(x) = u(x) - u_0(x)$$

$$\rightarrow -w_{xx} = f + (u_0(x))_{xx}$$

$$w(0) = 0$$

③ $\beta \neq 0$

$$-u_{xx} = f$$

$$u(0) = 0 \quad \leftarrow$$

$$u'(1) = \beta$$

$$\rightarrow \int_0^1 -u_{xx} v = \int_0^1 f v$$

$$\rightarrow \int_0^1 u_x v_x dx - \cancel{u_x v} \Big|_0^1 = \int_0^1 f v dx$$

$$\int_0^1 u_x v_x dx = \int_0^1 f v dx + \beta \cdot v(1)$$

$$-u_x(1)v(1)$$

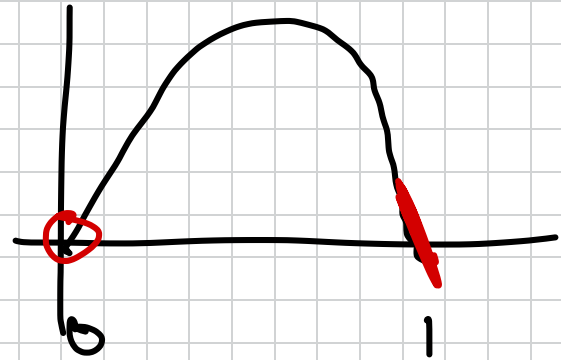
$$u^h = \sum u_j \phi_j$$

find u^h

$$\int_0^1 u_x^h \cdot (\phi_j)_x dx = \int_0^1 f \phi_j dx + \beta \cdot \phi_j(1) \quad \forall \phi_j$$

$$-u_{xx} = f$$

$$\text{let } u(x) = \sin(\pi x)$$



$$\Rightarrow u'(x) = \pi \cos \pi x$$

$$\Rightarrow u'(1) = -\pi$$

$$u(0) = 0$$

$$\left\{ \begin{array}{l} -u_{xx} = \pi^2 \sin \pi x \\ u(0) = 0 \\ u'(1) = -\pi \end{array} \right.$$

recommendation:

- ① β
- ② k apply
- ③ α

$$\begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 2 \\ -1 \\ \vdots \\ -1 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} + \begin{bmatrix} u_0 \\ u_1 \\ \vdots \\ u_n \end{bmatrix} = \begin{bmatrix} \alpha \\ f_1 \\ \vdots \\ f_n \end{bmatrix}$$

A u f

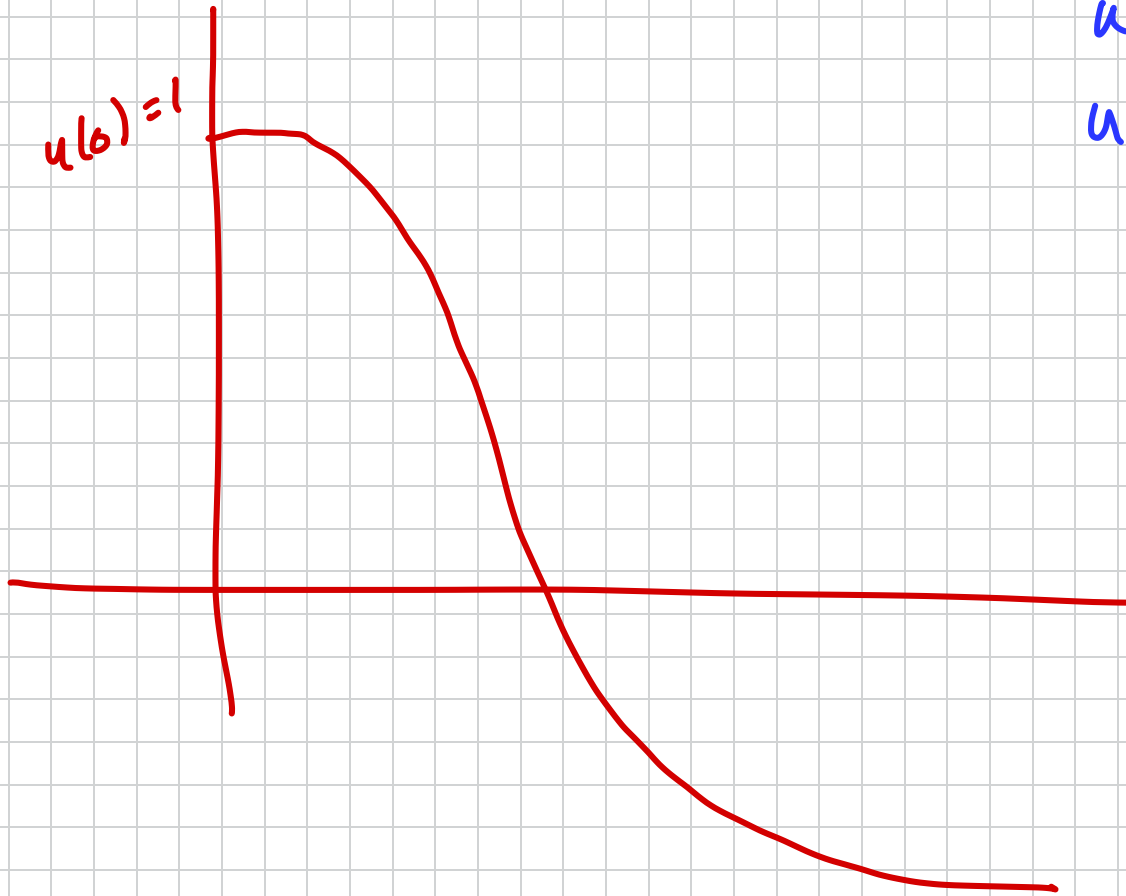
$$u = \cos \pi x$$



$$-u_{xx} = \pi^2 \cos \pi x$$

$$u(0) = 1$$

$$u'(1) = 0$$



$$u'(0) = 0$$