

Cost Analysis: Jacobi Iteration

- Recall our Jacobi iteration from Lec. 1, with $D := \text{diag}(A)$.
- We can express this in two ways,

Analysis:

$$\begin{aligned} \underline{x}_0 &= 0 \\ \text{for } k &= 1 : k_{\max} \\ \underline{x}_k &= \underline{x}_{k-1} + D^{-1}(\underline{b} - A\underline{x}_{k-1}) \end{aligned}$$

Practice:

$$\begin{aligned} \underline{x} &= 0 \\ \text{for } k &= 1 : k_{\max} \\ \underline{x} &= \underline{x} + D^{-1}(\underline{b} - A\underline{x}) \end{aligned}$$

- Two main questions arise re. complexity:

(1) How much work, w , per iteration?

(2) How many iterations, k ?

- The total work is $W = w k$.

- To address the first, consider more realistic loops:

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 $\underline{x} = 0, \underline{r} = \underline{b}$ 
for  $k = 1 : k_{\max}$ 
   $\rho = \|\underline{r}\|_2 = \sqrt{\underline{r}^T \underline{r}}$ 
  if  $\rho < tol$ , break.
   $\underline{x} = \underline{x} + D^{-1} \underline{r}$ 
   $\underline{r} = \underline{b} - A \underline{x}$ 
end

```

- A better approach is:

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 $\underline{x} = 0, \underline{r} = \underline{b}, \rho_0 = \|\underline{r}\|_2 = \sqrt{\underline{r}^T \underline{r}}$ 
for  $k = 1 : k_{\max}$ 
   $\rho = \|\underline{r}\|_2 = \sqrt{\underline{r}^T \underline{r}}$ 
  if  $\rho/\rho_0 < tol$ , break.
   $\underline{s} = D^{-1} \underline{r}$ 
   $\underline{x} = \underline{x} + \underline{s}$ 
   $\underline{r} = \underline{r} - A \underline{s}$ 
end

```

- **Q:** How many operations for each step, as a function of d ?

- Quick summary:

$$\begin{aligned}
 d = 1 : & \quad 9n \cdot k \\
 d = 2 : & \quad 13n \cdot k \\
 d = 3 : & \quad 17n \cdot k
 \end{aligned}$$

- We see that the cost *per iteration* is only weakly dependent on d !

- What about the *number* of iterations?

- To analyze this question, we'll need some norms to measure the error.
- Let's start with the vector 2-norm,

$$\|\underline{x}\|_2 := \sqrt{\underline{x}^T \underline{x}} = \left(\sum_j^n x_j^2 \right)^{\frac{1}{2}}. \quad (1)$$

- With this vector norm, we have an associated *matrix norm*,

$$\|A\|_2 := \max_{\underline{x} \in \mathbb{R}^n} \frac{\|A\underline{x}\|_2}{\|\underline{x}\|_2} \quad (2)$$

$$:= \max_{\|\underline{x}\|=1} \|A\underline{x}\|_2. \quad (3)$$

- We see that $\|A\|_2$ is identified with the *maximum stretching* (growth) of any input vector \underline{x} .
- For the case of $A = A^T$, we have $\|A\|_2 = \rho(A)$.
- Therefore, we know the 2-norm of A for our finite difference matrices!
- Which matrix do we need the 2-norm for to understand the error behavior of Jacobi iteration?