

Today's

- ID demo
- Apply ID to the SVD
- Potential matrices
 - low rank
- Rank in terms of functions

$\begin{bmatrix} \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{bmatrix}$

$= A \begin{bmatrix} \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{bmatrix}$

- HW due

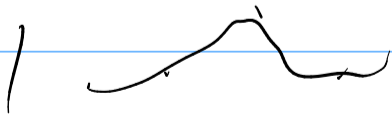
$$A = Q \underbrace{Q^T A}_{\text{low rank}}$$

$\square \quad \square \quad \square$

ID recap

A has rank k

$$A = A_{[k]} P$$



Goal recap

$$A \Pi = Q$$



ID Q vs ID A

What does row selection mean for the LRA?

$\swarrow Q$

$$A \approx Q Q^T A$$

run row ("transpose") ID on Q: $Q \approx P Q_{[j,:]}$

$$A \approx P Q_{[j,:]} Q^T A$$

\leftarrow $A_{[j,:]} \approx \cancel{P}_{[j,:]} Q_{[j,:]} Q^T A = Q_{[j,:]} Q^T A$

ID

$$P A_{[j,:]} = \underbrace{P Q_{[j,:]}}_{\approx Q} Q^T A \approx Q Q^T A \approx A$$

[Martinsson, Rokhlin, Tygert '06] $\approx Q$

Demo: Interpolative Decomposition

- There is a slight tradeoff here--which?
- How do we use the ID in the context of low-rank range finding?

What does the ID buy us?

Name a property that the ID has over other factorizations.

All our randomized tools have two stages:

1. Find ONB of approximate range
2. Do actual work only on approximate range

Complexity?

What is the impact of the ID?

Ability to replace computing QFA with $A_{\Sigma, \Gamma}$

$$\text{SVD } A_{[j_1:j]} = U \Sigma V^T$$

$$P A_{[j_1:j]} = P \underbrace{U \Sigma V^T}_{\text{? not orth.}}$$

ID-based Complexity Reduction

$$N \times k \begin{matrix} N \\ \boxed{A_{[j_1:j]}} \end{matrix}$$

How can we reduce factorization complexity with the ID?

- Assume we have P and J $A \approx PA_{[j_1:j]}$.

$$\begin{matrix} (A_{[j_1:j]})^T & = & \bar{Q} \bar{R} \\ N \times k & & N \times k \quad k \times k \end{matrix}$$

$$Z = P R^T$$


$N \times k \quad N \times k \quad k \times k$

$$Z = U \Sigma V^T$$

$N \times k \quad N \times k \quad k \times k \quad k \times k$

Leveraging the ID for SVD (II)

In what way does this give us an SVD of A ?

$$\begin{aligned} & U \Sigma (\bar{Q} \bar{V})^T \\ & \quad N \times N \quad k \times k \quad N \times k \quad k \times k \\ & = U \Sigma \bar{V}^T \bar{Q}^T \\ & = Z \bar{Q}^T \\ & = P R^T \bar{Q}^T \\ & = P A_{[:,i]} \approx A \end{aligned}$$


Leveraging the ID for SVD (III)

Q: Why did we need to do the row QR?

$$\text{SVD } A_{[j_1:j]} = U \Sigma V^T$$

$$P A_{[j_1:j]} = P U \Sigma V^T$$

? not orth ...

Where are we now?

- ▶ We have observed that we can make matvecs faster if the matrix has low-ish numerical rank
- ▶ In particular, it seems as though if a matrix has low rank, there is no end to the shenanigans we can play.
- ▶ We have observed that some matrices we are interested in (in some cases) have low numerical rank (cf. the point potential example)
- ▶ We have developed a toolset that lets us obtain LRAs and do useful work (using SVD as a proxy for “useful work”) in $O(N \cdot K^\alpha)$ time (assuming availability of a cheap matvec).

Next stop: Get some insight into *why* these matrices have low rank in the first place, to perhaps help improve our machinery even further.

Outline

Introduction

Dense Matrices and Computation

Tools for Low-Rank Linear Algebra

Rank and Smoothness

Local Expansions

Multipole Expansions

Rank Estimates

Proxy Expansions

Near and Far: Separating out High-Rank Interactions

Outlook: Building a Fast PDE Solver

Going Infinite: Integral Operators and Functional Analysis

Singular Integrals and Potential Theory

Boundary Value Problems

Back from Infinity: Discretization

Computing Integrals: Approaches to Quadrature

Going General: More PDEs

Punchline



What do (numerical) rank and smoothness have to do with each other?

If all outputs of an operator has a short expansion in
some basis, then that is a continuous
equivalent of "low rank".

← poly, Fourier, algebraic functions ...


Even shorter punchline?



Smoothing Operators

If the operations you are considering are *smoothing*, you can expect to get a lot of mileage out of low-rank machinery.

What types of operations are smoothing?

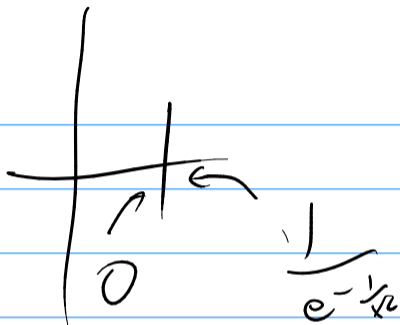
- $\frac{d}{dx}$: Derivatives	
\rightarrow not smoothing	$\mathcal{F}\{\partial_x f\}(\omega) = (i\omega) \mathcal{F}\{f\}(\omega)$
- Integrals	$\mathcal{F}\{\int f\}(\omega) = (i\omega)^{-1} \mathcal{F}\{f\}(\omega)$
\rightarrow smoothing	

Now: Consider some examples of smoothness, with justification.

How do we judge smoothness?

$$C^\omega, C^\infty, \dots, C^k, \dots, C^0$$

by the remainder term in the Taylor series

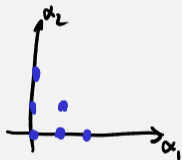


Recap: Multivariate Taylor

 \mathbb{R}^h

$$1D \text{ Taylor: } f(c+h) \approx \sum_{p=0}^k \frac{f^{(p)}(c)}{p!} h^p$$

$$f(\vec{c}+\vec{h}) \approx \sum_{|\alpha| \leq k} \frac{\partial^\alpha f(\vec{c})}{\alpha!} \vec{h}^\alpha$$



Multi-Index

$$\alpha = (\alpha_1, \dots, \alpha_n)$$

$$\partial^\alpha f = \frac{\partial^{\alpha_1} \dots \partial^{\alpha_n}}{\partial x_1^{\alpha_1} \dots \partial x_n^{\alpha_n}} f$$

$$|\alpha| = |\alpha_1| + \dots + |\alpha_n|$$

$$\alpha! = \alpha_1! \dots \alpha_n!$$

$$\vec{h}^\alpha = h_1^{\alpha_1} \dots h_n^{\alpha_n}$$

Taylor and Error (I)

How can we estimate the error in a Taylor expansion?

(go back to 1D for simplicity)

$$\left| f(c+h) - \sum_{p=0}^k \frac{f^{(p)}(c)}{p!} h^p \right|$$
$$= \left| \sum_{p=k+1}^{\infty} \frac{f^{(p)}(c)}{p!} h^p \right| \leftarrow \text{if } f \text{ analytic}$$

Taylor and Error (II)

Now suppose that we had an estimate that $\left| \frac{f^{(p)}(c)}{p!} h^p \right| \leq \beta \cdot \beta^p$

$$\left| \sum_{p=k+1}^{\infty} \frac{f^{(p)}(c)}{p!} h^p \right| \leq \sum_{p=k+1}^{\infty} \left| \frac{f^{(p)}(c)}{p!} h^p \right| = \sum_{p=k+1}^{\infty} \beta^p = \frac{1}{1-\beta} \cdot \beta^{k+1}$$

Useful for
small enough
 β

Connect Taylor and Low Rank

Can Taylor help us establish low rank of an interaction?

